

# POISSON AND QUASI-POISSON STRUCTURES FOR NONABELIAN INTEGRABLE SYSTEMS

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# Outline

## 1 Introduction on Poisson brackets

1.1 Poisson brackets – A primer

1.2 Poisson brackets (and manifolds) in Integrable Systems

2 Nonabelian systems

3 (Not a) conclusion

# What is a Poisson bracket?

We all know where this story was born



S.D. Poisson (1809)

$$f_i(t, q_1, q_2, \dots, q_n, p_1, \dots, p_n) = a_i \text{ (const.)}$$

$$(f_j, f_k) = \sum_{l=1}^n \left( \frac{\partial f_j}{\partial q_l} \frac{\partial f_k}{\partial p_l} - \frac{\partial f_j}{\partial p_l} \frac{\partial f_k}{\partial q_l} \right) = \text{const.}$$



C.G.J. Jacobi (1830)

$$(A, (B, C)) + (B, (C, A)) + (C, (A, B)) = 0$$

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# What is a Poisson bracket?

## Definition (Poisson bracket)

A *Poisson algebra* over a (commutative) ring (with unit)  $\mathbb{K}$  is a triple  $(A, \cdot, \{-, -\})$  where  $(A, \cdot)$  is an associative  $\mathbb{K}$ -algebra and  $(A, \{-, -\})$  is a  $\mathbb{K}$ -Lie algebra, such that

$$\{a, b \cdot c\} = \{a, b\} \cdot c + b \cdot \{a, c\}$$

for any  $a, b, c \in A$ .

- 1  $\{\alpha a + \beta b, c\} = \alpha\{a, c\} + \beta\{b, c\}$  (bi)linearity
- 2  $\{a, b\} = -\{b, a\}$  skewsymmetry
- 3  $\{a, \{b, c\}\} = \{\{a, b\}, c\} + \{b, \{a, c\}\}$  Jacobi identity
- 4  $\{a, bc\} = \{a, b\}c + b\{a, c\}$  Leibniz property

**Jargon** A Lie bracket which is also a derivation

# What *really* is a Poisson bracket?

A (mechanical, physical, ...) system: (configuration)/phase/fields space  $P$

A way to extract information from the system: “observables”,  
 $f \in C^\infty(P)$

- 1 A Lie algebra for the observables
- 2 An (infinitesimal) action of  $C^\infty(P)$  on  $P$  (by derivations!,  $X_h$ )

such that

$$X_{\{f,g\}} = -[X_f, X_g]$$

# What *really* is a Poisson bracket?

A (mechanical, physical, ...) system: (configuration)/phase/fields space  $\mathcal{A}$

A way to extract information from the system: “observables”,  $f \in \mathcal{F}$




- 1 A Lie algebra for the observables
- 2 An (infinitesimal) action of  $\mathcal{F}$  on  $\mathcal{A}$  (by derivations!,  $X_h$ )

such that

$$X_{\{f,g\}} = -[X_f, X_g]$$

TWO roles for ONE bracket!

# Poisson brackets in Integrable Systems

- ▶ Finite dimensional systems (systems of ODEs): classical picture 
- ▶ Systems of PDEs: formal calculus of variations 
  - ▶ Poisson structure is given by (pseudo)differential operators
  - ▶ Modern theory of Integrable Systems: Zakharov, Shabat, Magri, ..., Dubrovin, ...
  - ▶ Algebraic approach: Poisson vertex algebras (De Sole, Kac and collabs.
- ▶ Systems of differential-difference equations: technical difficulties but similar to PDEs (Kuperschmidt 1980) 



# Outline

1 Introduction on Poisson brackets

2 Nonabelian systems

2.1 Motivation

2.2 Algebraic picture

2.3 Geometric picture

3 (Not a) conclusion

# The path to nonabelian systems

$$\begin{cases} \dot{u} = u^2 v - v u^2 \\ \dot{v} = 0 \end{cases}$$

is integrable for  $u, v \in \mathfrak{gl}(n), \forall n$ .

► What for?

- 1 Rigid body:  $u \in \mathfrak{so}(n), v = \text{diag}(a_1, \dots, a_n)$  (Manakov)
- 2 Nonabelian (periodic) Volterra chain:  $u, v \in \mathfrak{gl}(n \cdot m), u_k, v_k \in \mathfrak{gl}(m)$ .

$$u = \begin{pmatrix} 0 & 0 & \cdots & u_n \\ u_1 & 0 & \cdots & 0 \\ & & & \vdots \\ 0 & u_2 & 0 & \vdots \\ \vdots & & & \ddots \\ \vdots & 0 & u_3 & \ddots \end{pmatrix} \quad v = \begin{pmatrix} 0 & -v_1 & 0 & \cdots \\ 0 & 0 & -v_2 & 0 \\ \vdots & \vdots & 0 & -v_3 \\ -v_n & 0 & \cdots & \ddots \end{pmatrix}$$

$$(u_k)_t = v_k u_{k+1} u_k - v_{k-1} u_k u_{k-1}$$

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- Integrable in which sense?

Lax integrability

$$L := v\lambda - u$$

$$A := \frac{u^2}{\lambda}$$

$$L_t = [L, A]$$

$\text{tr} L^k$  are conserved quantities

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- ▶ Integrable in which sense?

Lax integrability

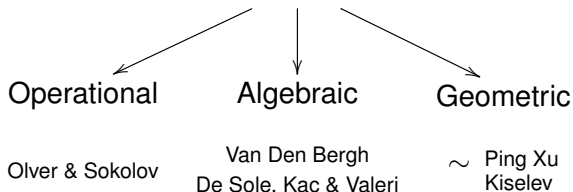
$$L := v\lambda - u \qquad A := \frac{u^2}{\lambda}$$

$$L_t = [L, A] \qquad \text{tr} L^k \text{ are conserved quantities}$$

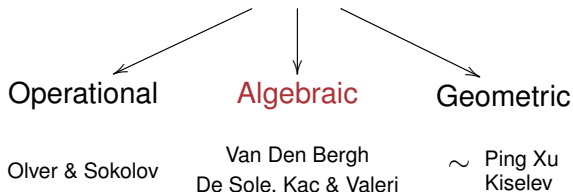
And then we forget about the original matrix formulation and deal only with non-commuting functions  $u(t), v(t)$ .

- ▶ PDE case:  $u_t = u_{3x} + uu_x + u_x u$  (nonabelian KdV)
- ▶ DΔE case:  $u_t = u_1 u - u u_{-1}$  (nonabelian (open) Volterra)

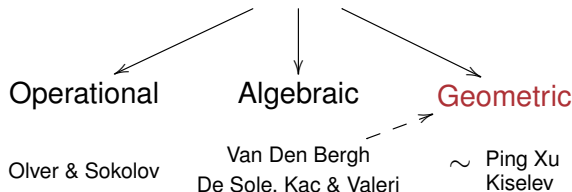
# But what does it mean to be a Hamiltonian system?



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# The setting

We keep the crucial difference between  $\mathcal{A}$  and  $\mathcal{F}$  (and yes, now it applies to ODEs too)

	$\mathcal{A}$	$\mathcal{F}$
ODEs	Noncomm. Laurent polyn. $\mathcal{A} = \frac{\mathbb{K}\langle\{u^i, (u^i)^{-1}\}_{i=1,\dots,\ell}\rangle}{\langle u^j (u^j)^{-1} - 1 \rangle}$	$\frac{\mathcal{A}}{[\mathcal{A}, \mathcal{A}]}$ $f \in \mathcal{A}, \text{tr } f \in \mathcal{F}$
PDEs	Noncomm. L. differential p. $\mathcal{A} = \frac{\mathbb{K}\langle\{u_{nx}^i, (u_{nx}^i)^{-1}\}_{i=1,\dots,\ell, n \geq 0}\rangle}{\langle u_{kx}^j (u_{kx}^j)^{-1} - 1 \rangle}$	$\frac{\mathcal{A}}{[\mathcal{A}, \mathcal{A}] + \partial \mathcal{A}}$ $\int \text{tr } f \in \mathcal{F}$
D $\Delta$ E	Noncomm. L. difference p. $\mathcal{A} = \frac{\mathbb{K}\langle\{u_n^i, (u_n^i)^{-1}\}_{i=1,\dots,\ell, n \in \mathbb{Z}}\rangle}{\langle u_m^j (u_m^j)^{-1} - 1 \rangle}$	$\frac{\mathcal{A}}{[\mathcal{A}, \mathcal{A}] + (\mathcal{S} - 1)\mathcal{A}}$ $\int \text{tr } f \in \mathcal{F}$



# The setting

We focus on the ODEs/“ultralocal” case for simplicity. Difference case in the parallel session.

Scalar multiplicative operators  $K: \mathcal{A} \rightarrow \mathcal{A}$

$$\begin{aligned} \mathbf{l}_a \mathbf{r}_b f &:= a f b & \mathbf{c}_a &:= \mathbf{l}_a - \mathbf{r}_a & \mathbf{a}_a &:= \mathbf{l}_a + \mathbf{r}_a \\ \mathbf{l}_a \mathbf{l}_b &= \mathbf{l}_{ab} & \mathbf{r}_a \mathbf{r}_b &= \mathbf{r}_{ba} & \mathbf{l}_a \mathbf{r}_b &= \mathbf{r}_b \mathbf{l}_a \end{aligned}$$

Double derivative  $\frac{\partial}{\partial u}: \mathcal{A} \rightarrow \mathcal{A} \otimes \mathcal{A}$

$$\begin{aligned} \frac{\partial}{\partial u^s} ((u^1)^{\pm 1} \dots (u^n)^{\pm 1}) &= \sum' \delta_{i_k, s} (u^1)^{\pm 1} \dots (u^{k-1})^{\pm 1} \otimes (u^{k+1})^{\pm 1} \dots (u^n)^{\pm 1} \\ &\quad - \sum'' \delta_{i_k, s} (u^1)^{\pm 1} \dots (u^{k-1})^{\pm 1} (u^k)^{-1} \otimes (u^k)^{-1} (u^{k+1})^{\pm 1} \dots (u^n)^{\pm 1} \end{aligned}$$

$$\frac{\partial}{\partial u}(ab) = \frac{\partial a}{\partial u} b + a \frac{\partial b}{\partial u}$$

# The setting

**Operations in  $\mathcal{A} \otimes \mathcal{A}$**  Let  $A \in \mathcal{A} \otimes \mathcal{A}$ , with Sweedler's notation,  $A' \otimes A''$  ( $= \sum_k A'_k \otimes A''_k$ ). Let  $a, b$  in  $\mathcal{A}$ .

$$\begin{aligned}
 a(b \otimes c)d &= ab \otimes cd & a \star (b \otimes c) \star d &= bd \otimes ac \\
 (a \otimes b) \bullet (c \otimes d) &= ac \otimes db & \tau_{(12)}(a \otimes b) &= b \otimes a \\
 m(a \otimes b) &= ab
 \end{aligned}$$

Note that  $\bullet$  product works as composition of multiplication operators ( $l_a r_b \circ l_c r_d$ ). We can translate between (noncommutative) multiplication operators and elements of  $\mathcal{A} \otimes \mathcal{A}$  by

$$l_a r_b \leftrightarrow a \otimes b$$

## Operations in $\mathcal{A}^{\otimes 3}$

$$(a \otimes b) \otimes_1 c = a \otimes c \otimes b \quad \tau_{(123)}(a \otimes b \otimes c) = c \otimes a \otimes b$$

# Double Poisson algebras

Van Den Bergh, 2008

Define a **double bracket**  $\{\{-, -\}\}: \mathcal{A} \times \mathcal{A} \rightarrow \mathcal{A} \otimes \mathcal{A}$  such that

- 1  $\{\{a, \beta b + \gamma c\}\} = \beta \{\{a, b\}\} + \gamma \{\{a, c\}\}$
- 2  $\{\{a, bc\}\} = b \{\{a, c\}\} + \{\{a, b\}\} c$  (derivation in the second entry)
- 3  $\{\{b, a\}\} = -\tau_{(12)} \{\{a, b\}\}$  (skewsymmetry)
- 4 Let  $\{\{a, b \otimes c\}\}_L := \{\{a, b\}\} \otimes c$ . Then

$$\{\{a, \{\{b, c\}\}\}_L + \tau_{(123)} (\{\{b, \{\{c, a\}\}\}\}_L) + \tau_{(123)}^2 (\{\{c, \{\{a, b\}\}\}\}_L) = 0$$

(double Jacobi identity). We denote the expression on the RHS  $\{\{a, b, c\}\}$ .

Given a double bracket among the generators of  $\mathcal{A}$ ,

$$\{\{f, g\}\} = \sum_{i,j=1 \dots \ell} \frac{\partial g}{\partial u^i} \bullet \{\{u^i, u^j\}\} \bullet \tau_{(12)} \left( \frac{\partial f}{\partial u^j} \right)$$

# Double Poisson algebras

## The Poisson bracket

### Theorem

Let  $(\mathcal{A}, \{\{-, -\}\})$  be a double Poisson algebra. Then

- 1 It defines a Lie algebra structure on  $\mathcal{F}$ , by

$$\{F, G\} = \text{tr } m(\{\{f, g\}\})$$

for  $F = \text{tr } f$ ,  $G = \text{tr } g$ .

- 2 It defines an action of  $\mathcal{F}$  on  $\mathcal{A}$  by derivations, by

$$X_F(a) = m \left( X_F^i \star \frac{\partial a}{\partial u^i} \right)$$

and

$$X_F^i = -m \left( \{\{f, u^i\}\} \right)$$

- 3 The two are compatible:  $X_{\{F, G\}} = -[X_F, X_G]$ .

# Double Poisson algebras

## Sketch of the proof

Well-defined bracket Vanishing on commutators

Skewsymmetry of  $\{-, -\}$  Let  $\{\{f, g\}\} = B' \otimes B''$ . Then

$$\begin{aligned} \{G, F\} &= -\operatorname{tr} m(\{\{g, f\}\}) = +\operatorname{tr} m(\tau_{(12)}\{\{f, g\}\}) = \\ \operatorname{tr} B'' B' &= \operatorname{tr} B' B'' = -\{F, G\}. \end{aligned}$$

Jacobi identity of  $\{-, -\}$  We have

$$\begin{aligned} \{F, \{G, H\}\} - \{G, \{F, H\}\} - \{\{F, G\}, H\} = \\ \operatorname{tr} m((m \otimes 1)\{\{f, g, h\}\} - (1 \otimes m)\{\{g, f, h\}\}) = 0 \end{aligned}$$

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# Double Poisson algebras

## Examples and Hamiltonian systems

### 1 Scalar case

$$\triangleright c_u \leftrightarrow \{\{u, u\}\} = u \otimes 1 - 1 \otimes u$$

$$\triangleright l_u r_{u^2} - l_{u^2} r_u \leftrightarrow \{\{u, u\}\} = u \otimes u^2 - u^2 \otimes u$$

### 2 Two-components

$$\begin{cases} \dot{u} = u^2 v - v u^2 \\ \dot{v} = 0 \end{cases}$$

is Hamiltonian with respect to

$$\{\{u, u\}\} = u \otimes v - v \otimes u$$

$$\{\{u, v\}\} = 0$$

$$\{\{v, u\}\} = 0$$

$$\{\{v, v\}\} = 0$$

and

$$H = \frac{1}{2} \operatorname{tr} u^2$$



# Double quasi-Poisson algebras

Let  $A$  be an associative algebra whose units admits a finite decomposition in orthogonal idempotents  $1 = \sum e_s$ ,  $e_s e_t = \delta_{st} e_s$ , and  $\{\{-, -\}\}$  a linear double bracket (skewsymmetric, not Jacobi) satisfying

$$\begin{aligned} \{\{a, b, c\}\} = \alpha \sum_s & (c e_s a \otimes e_s b \otimes e_s - c e_s a \otimes e_s \otimes b e_s \\ & - c e_s \otimes a e_s b \otimes e_s + c e_s \otimes a e_s \otimes b e_s \\ & - e_s a \otimes e_s b \otimes e_s c + e_s a \otimes e_s \otimes b e_s c \\ & + e_s \otimes a e_s b \otimes e_s c - e_s \otimes a e_s \otimes b e_s c) \end{aligned}$$

Then  $(A, \{\{-, -\}\})$  is a *double quasi-Poisson algebra*.

## Examples

- ▶ Scalar case  $\{\{u, u\}\} = u^2 \otimes 1 - 1 \otimes u^2$
- ▶ Two components (Kontsevich)

$$\{\{u, u\}\} = 1 \otimes u^2 - u^2 \otimes 1$$

$$\{\{u, v\}\} = u \otimes v - v \otimes u - 1 \otimes uv - vu \otimes 1$$

$$\{\{v, u\}\} = uv \otimes 1 + 1 \otimes vu + u \otimes v - v \otimes u$$

$$\{\{v, v\}\} = v^2 \otimes 1 - 1 \otimes v^2$$

# Double quasi-Poisson algebras

Let  $\mathcal{A}$  as above, and  $\{\{-, -\}\}$  a linear double bracket (skewsymmetric, not Jacobi) satisfying

$$\begin{aligned} \{\{a, b, c\}\} = & \alpha (ca \otimes b \otimes 1 - ca \otimes 1 \otimes b \\ & - c \otimes ab \otimes 1 + c \otimes a \otimes b \\ & - a \otimes b \otimes c + a \otimes 1 \otimes bc \\ & + 1 \otimes ab \otimes c - 1 \otimes a \otimes bc) \end{aligned}$$

Then  $(\mathcal{A}, \{\{-, -\}\})$  is a *double quasi-Poisson algebra*.

## Examples

- ▶ Scalar case  $\{\{u, u\}\} = u^2 \otimes 1 - 1 \otimes u^2$
- ▶ Two components (Kontsevich)

$$\begin{aligned} \{\{u, u\}\} &= 1 \otimes u^2 - u^2 \otimes 1 & \{\{u, v\}\} &= u \otimes v - v \otimes u - 1 \otimes uv - vu \otimes 1 \\ \{\{v, u\}\} &= uv \otimes 1 + 1 \otimes vu + u \otimes v - v \otimes u & \{\{v, v\}\} &= v^2 \otimes 1 - 1 \otimes v^2 \end{aligned}$$

# Double quasi-Poisson algebras

## Double quasi-Poisson algebras and Poisson brackets

A double quasi-Poisson algebra defines a Poisson bracket too!

- ▶ The double bracket is skewsymmetric  $\Rightarrow$  the bracket on  $\mathcal{F}$  is skewsymmetric
- ▶ We have  $(m \otimes 1)\{\{a, b, c\}\} = (1 \otimes m)\{\{a, b, c\}\} = 0 \Rightarrow$  the bracket on  $\mathcal{F}$  satisfies the Jacobi identity
- ▶ There is the usual isomorphism between  $(\mathcal{F}, \{-, -\})$  and  $(\text{Der } \mathcal{A}, [-, -])$  (proof in the geometric picture)

# Poisson brackets and Poisson bivectors

## The main idea

There is a rich and well-established machinery to read Hamiltonian systems with geometrical (Poisson) glasses:

- ▶ Hamiltonian operator  $\iff$  Poisson bivector
- ▶ Poisson bivector  $\Rightarrow$  Poisson brackets, Hamiltonian vector fields (equations of motion), Poisson cohomology (theory of deformations, integrability...)

Can we do the same (or something similar)?

- 1 Poly-vector fields and Schouten brackets
- 2 Poisson bivectors
- 3 Define PB, Hamiltonian vector fields, ... using only Schouten brackets

# $\theta$ formalism

When differential graded manifolds enter the game

“Well”-known fact  $T^*[1]M \cong \Lambda^\bullet TM$ , and  $T^*[1]M$  is a (odd) symplectic manifold with canonical bracket  $\iff$  Schouten bracket on  $\Lambda^\bullet TM$

**Concrete construction** Let  $\{u^i\}$  be a coordinate chart on  $M$ , their canonical conjugate variables are  $\{\theta_i\}$ .

$$\deg u = 0 \quad \deg \theta = 1 \quad \deg f = |f|$$

**Normally**,  $u$ 's are commuting variables and  $\theta$ 's Grassmann variables.  
**However**, in this noncommutative context neither have assigned parity under the product. Yet, derivations are graded and the trace operation is.

$$\hat{\mathcal{A}} := \mathcal{A}[\{\theta_i\}] \quad \hat{\mathcal{F}} := \frac{\hat{\mathcal{A}}}{[\hat{\mathcal{A}}, \hat{\mathcal{A}}]_{(gc)}}$$

with  $[f, g]_{(gc)} = fg - (-1)^{|f||g|}gf$ , namely  $\text{tr } fg = (-1)^{|f||g|} \text{tr } gf$

# The Schouten bracket

Let us denote  $\hat{A}^p$  (resp.  $\hat{F}^p$ ) the homogeneous component of degree  $p$  of  $\hat{A}$  ( $\hat{F}$ )

## Double Schouten bracket

Let  $[[-, -]]: \hat{A}^p \times \hat{A}^q \rightarrow (\hat{A} \otimes \hat{A})^{p+q-1}$

$$[[f, g]] := \sum_{l=1}^{\ell} \frac{\partial g}{\partial u^l} \bullet \tau_{(12)} \left( \frac{\partial f}{\partial \theta_l} \right) + (-1)^{|g|} \frac{\partial g}{\partial \theta_l} \bullet \tau_{(12)} \left( \frac{\partial f}{\partial u^l} \right)$$

with  $(a \otimes b) \bullet (c \otimes d) = (-1)^{(|c|+|d|)|b|} ac \otimes db$  and  $\tau_{(12)}(a \otimes b) = (-1)^{|a||b|} b \otimes a$

Then

- ▶  $[[g, f]] = -(-1)^{(|f|-1)(|g|-1)} \tau_{(12)} [[f, g]]$
- ▶  $[[f, [[g, h]]]_L = [[[f, g], h]]_L + (-1)^{(|f|-1)(|g|-1)} [[g, [[f, h]]]_R$   
with  $[a, b \otimes c]_L = (-1)^{(|a|-1)|c|} [a, b] \otimes c$ ,  $[a, b \otimes c]_R = b \otimes [a, c]$ ,  $[a \otimes b, c]_L = [a, c] \otimes_1 c$
- ▶  $[[f, gh]] = g[[f, h]] + (-1)^{(|f|-1)|h|} [[f, g]]h$

# The Schouten bracket

$$[-, -]: \hat{\mathcal{F}}^p \times \hat{\mathcal{F}}^q \rightarrow \hat{\mathcal{F}}^{p+q-1}$$

with  $A = \text{tr } a$ ,  $B = \text{tr } b$

$$[A, B] := \text{tr } m(\llbracket a, b \rrbracket)$$

Then

- ▶  $[F, G] = 0$  if  $F, G \in \hat{\mathcal{F}}^0 = \mathcal{F}$
- ▶  $[X, Y]$  coincides with commutator of vector fields if  $X, Y \in \hat{\mathcal{F}}^1$
- ▶  $[X, B] = \mathcal{L}_X(B)$
- ▶  $[B, A] = -(-1)^{(|A|-1)(|B|-1)}[A, B]$
- ▶  $[A, [B, C]] = \llbracket [A, B], C \rrbracket + (-1)^{(|A|-1)(|B|-1)}[B, [A, C]]$

# From the bivector to the bracket

## Operators and bivectors

We say that a bivector  $P$  is *Poisson* if

$$[P, P] = 0$$

Given a multiplicative operator  $K: \mathcal{A}^\ell \rightarrow \mathcal{A}^\ell$  we associate the bivector

$$P = \sum_{i,j=1,\dots,\ell} \frac{1}{2} \text{tr} \left( \theta_i K^{ij}(\theta_j) \right)$$

Example  $K = 1_u r_{u^2} - 1_{u^2} r_u$ ,  $P = \text{tr}(\theta u \theta u^2)$

## Theorem

$$[P, P] = 0 \iff \{ \{ -, -, - \} \} = 0$$

for  $\{ \{ u^i, u^j \} \} = K_L^{ij} \otimes K_R^{ji}$ .



# From the bivector to the bracket

## The Poisson bracket

Once we have the Schouten bracket and a reasonable definition of Poisson bivector, we are done: for  $F, G$  in  $\mathcal{F}$

$$\{F, G\} := [[P, F], G]$$

- ▶ Skewsymmetry: from graded skewsymmetry of  $[-, -]$
- ▶ Jacobi identity:  $\{F, \{G, H\}\} + \text{cyclic} \iff [[[[P, P], F], G], H]$  from graded Jacobi of  $[-, -]$ .  $P$  Poisson  $\Rightarrow$  Jacobi identity
- ▶ Action on  $\mathcal{A}$ : the Hamiltonian vector field for  $H$  is  $[P, H] = -\text{tr}(X_H)^i \theta_i$ . Then the action on  $\mathcal{A}$  is

$$X_H(f) = m([X_H, f])$$

# Outline

- 1 Introduction on Poisson brackets
- 2 Nonabelian systems
- 3 (Not a) conclusion**

# (Not a) conclusion

Hamiltonian structures beyond Poisson ones?

We have seen the case of double quasi-Poisson algebras:  $[P, P] \neq 0$  but  $\{F, G\} = [[P, F], G]$  a Poisson bracket.

Indeed,

$$\text{qPoisson} \iff [[P, P], F] = 0 \quad \forall F \in \mathcal{F}$$

But what we actually need is

$$\text{Jacobi} \iff [[[[P, P], F], G], H] = 0 \quad \forall F, G, H$$

$$\text{Action on } \mathcal{A} \iff [[[[P, P], F], G] = 0 \quad \forall F, G$$

Are there more general structures? And integrable systems with them?

# In the parallel session...

According to the interest

- ▶ Nonabelian integrable difference systems
  - 1 Difference operators and *multiplicative double PVA*
  - 2 Examples
- ▶ Poisson “geometry”
  - 1 Poly-vector fields and  $\theta$  formalism
  - 2 Poisson cohomology

Thanks for your attention!

# Finite-dimensional case

Classical stuff. But also, the birthplace of Poisson geometry

## Hamiltonian mechanics

The phase space  $P$  with  $\dim P = 2n$ , coordinates  $(q^i, p_i)$ ,  $i = 1, \dots, n$ .

The Hamiltonian function  $H(q, p)$

$$\begin{cases} \dot{q}^i = \frac{\partial H}{\partial p_i} \\ \dot{p}_i = -\frac{\partial H}{\partial q^i} \end{cases} \quad X_h = \begin{pmatrix} \mathbf{0} & \mathbf{1}_n \\ -\mathbf{1}_n & \mathbf{0} \end{pmatrix} \begin{pmatrix} \frac{\partial H}{\partial q} \\ \frac{\partial H}{\partial p} \end{pmatrix}$$

$$\{f, g\} = \sum_{i,j=1}^n \frac{\partial f}{\partial z^i} \{z^i, z^j\} \frac{\partial g}{\partial z^j}$$

with

$$\{q^i, q^j\} = \{p_i, p_j\} = 0$$

$$\{q^i, p_j\} = \delta_j^i$$

# Finite-dimensional case

Classical stuff. But also, the birthplace of Poisson geometry

Let  $F_1$  such that  $\{F_1, H\} = 0$ . We call  $F_1$  a **first integral** of the system: it is a constant of the motion and its associated Hamiltonian vector field is a **symmetry** of the system

$$[X_h, X_{F_1}] = 0$$

## Theorem (Jacobi)

*Let  $F_1, F_2$  be first integrals of the Hamiltonian system  $X_h$ . Then  $\{F_1, F_2\}$  is a first integral too*

## Definition (Liouville integrability)

Let  $F_0 = h, F_1, \dots, F_{n-1}$  functionally independent first integrals of  $X_h$ , such that

$$\{F_i, F_j\} = 0 \quad \forall i, j.$$

Then we call the system  $X_h$  integrable.

# Finite-dimensional case

Classical stuff. But also, the birthplace of Poisson geometry

Let  $M$  be a smooth manifold,  $\dim M = 2n + r$ , and let  $\Pi \in \Gamma(M, \Lambda^2 TM)$  such that

$$[\Pi, \Pi] = 0$$

(where  $[-, -]$  is the Schouten bracket  $\Lambda^p TM \rightarrow \Lambda^q TM \rightarrow \Lambda^{p+q-1} TM$ ).

Then

$$\{f, g\} := \Pi(df, dg)$$

$$X_f := \Pi^\# df$$

$(M, \Pi)$  is a Poisson manifold,  $[\Pi, -] = d_\Pi$  the Poisson differential, splitting theorem, ...



# Hamiltonian PDEs

The modern theory of Integrable Systems

(for simplicity, just one spatial dimension)

$$u(x, t): \Sigma \times \mathbb{R} \rightarrow M \qquad u_x := \partial_x u(x, t)$$

$$\frac{\partial u^i}{\partial t} = F^i(u, u_x, u_{2x}, \dots)$$

Space of fields  $\mathcal{A}$ : differential polynomials/functions, densities of local functionals

$$f \in \mathcal{A} = C^\infty(\{u^i\})[\{u_{kx}^i\}]$$

with  $k > 0$  and  $i = 1, \dots, \ell$  (# of components,  $\dim M$ )

Local functionals  $F = \int f$

$$F \in \mathcal{F} = \frac{\mathcal{A}}{\partial \mathcal{A}}$$



# Hamiltonian PDEs

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$$F \in \mathcal{F} = \frac{\mathcal{A}}{\partial \mathcal{A}}$$

# Hamiltonian PDEs

The modern theory of Integrable Systems

(Proto)typical example: KdV

$$u_t = uu_x + u_{3x}$$

is (bi)Hamiltonian, in the sense

$$u_t = P_1 \left( \frac{\delta H_1}{\delta u} \right) = P_2 \left( \frac{\delta H_0}{\delta u} \right)$$

for

$$H_1 = \frac{1}{2} \int \left( \frac{u^3}{3} - u_x^2 \right)$$

$$P_1 = \partial$$

$$H_0 = \frac{1}{2} \int u^2$$

$$P_2 = \frac{1}{3} (2u\partial + u_x) + \partial^3$$

# Hamiltonian PDEs

The modern theory of Integrable Systems

$$\{H_0, H_1\}_{1,2} = 0 \text{ for } \{-, -\}_{1,2}: \mathcal{F} \times \mathcal{F} \rightarrow \mathcal{F}$$

$$\{F, G\}_{1,2} := \int \left[ \frac{\delta F}{\delta u} P_{1,2} \left( \frac{\delta G}{\delta u} \right) \right]$$

The bracket (called by the community “Poisson bracket”)

- ▶ is a Lie algebra bracket
- ▶ cannot be a derivation on  $\mathcal{F}$  (no product there)
- ▶ defines an action of  $\mathcal{F}$  on  $\mathcal{A}$  by derivations:

$$\left( \partial^k X_H \right) \frac{\partial}{\partial u_{kx}} \text{ for } X_H = P \left( \frac{\delta H}{\delta u} \right) = u_t$$

- ▶  $X_{\{F,G\}} = -[X_F, X_G]$



# Differential-difference systems

For a discrete space

(for simplicity, just one spatial dimension)

$$u(n, t): \Gamma \subseteq \mathbb{Z} \times \mathbb{R} \rightarrow M \quad Su(n, t) = u(n+1, t) =: u_1$$

$$\frac{\partial u^i}{\partial t} = F^i(u, u_1, u_{-1}, \dots)$$

Space of fields  $\mathcal{A}$ : difference polynomials/functions, densities of local functionals

$$f \in \mathcal{A} = \mathbb{K}[\{u_n^i\}]$$

with  $n \in \mathbb{Z}$  and  $i = 1, \dots, \ell$  (# of components,  $\dim M$ )

Local functionals  $F = \int f$  (in fact,  $\sum_n f(u(n))$ )

$$F \in \mathcal{F} = \frac{\mathcal{A}}{(S-1)\mathcal{A}} \quad \left( \int Sf = \int f \right)$$

# Differential-difference systems

For a discrete space

(Proto)typical example: Volterra chain

$$u_t = uu_1 - uu_{-1}$$

is (bi)Hamiltonian, in the sense

$$u_t = K_1 \left( \frac{\delta H_1}{\delta u} \right) = K_2 \left( \frac{\delta H_0}{\delta u} \right)$$

for

$$\frac{\delta F}{\delta u} = \sum_n S^{-n} \frac{\partial f}{\partial u_n}$$

$$H_1 = \frac{1}{2} \int u \quad H_0 = \frac{1}{2} \int \log u$$

$$K_1 = u (S - S^{-1}) u$$

$$K_2 = u (SuS + uS + Su$$

$$-uS^{-1} - S^{-1}u - S^{-1}uS^{-1}) u$$

# Differential-difference systems

For a discrete space

$$\{H_0, H_1\}_{1,2} = 0 \text{ for } \{-, -\}_{1,2}: \mathcal{F} \times \mathcal{F} \rightarrow \mathcal{F}$$

$$\{F, G\}_{1,2} := \int \left[ \frac{\delta F}{\delta u} K_{1,2} \left( \frac{\delta G}{\delta u} \right) \right]$$

This “Poisson bracket”, again,

- ▶ is a Lie algebra bracket
- ▶ cannot be a derivation on  $\mathcal{F}$  (no product there)
- ▶ defines an action of  $\mathcal{F}$  on  $\mathcal{A}$  by derivations:

$$\left( S^k X_H \right) \frac{\partial}{\partial u_n} \text{ for } X_H = K \left( \frac{\delta H}{\delta u} \right) = u_t$$

- ▶  $X_{\{F,G\}} = -[X_F, X_G]$

