

Advanced Transition-Based Parsing Techniques

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Based on previous tutorials with Ryan McDonald



Overall Plan

- 1. Basic notions of dependency grammar and dependency parsing
- 2. Graph-based and transition-based dependency parsing
- 3. Advanced graph-based parsing techniques
- 4. Advanced transition-based parsing techniques
- 5. Neural network techniques in dependency parsing
- 6. Multilingual parsing from raw text to universal dependencies



Plan for this Lecture

Improved learning and inference

- Beam search and structured prediction
- Easy-first parsing
- Dynamic oracles
- Non-projective parsing using online reordering
- Joint morphological and syntactic analysis



Transition-Based Parsing Trade-Off

- Advantages:
 - Highly efficient parsing linear time complexity with constant time oracles and transitions
 - Rich history-based feature representations no rigid constraints from inference algorithm
- Drawback:
 - Sensitive to search errors and error propagation due to greedy inference and local learning
- The major question in transition-based parsing has been how to improve learning and inference, while maintaining high efficiency and rich feature models



Beam Search

Maintain the k best hypotheses [Johansson and Nugues 2006]:

Parse (w_1, \ldots, w_n) 1 Beam $\leftarrow \{([]_S, [0, 1, \ldots, n]_B, \{\})\}$ 2 while $\exists c \in \text{Beam} [B_c \neq []]$ 3 foreach $c \in \text{Beam}$ 4 foreach t5 Add(t(c), NewBeam)6 Beam $\leftarrow \text{Top}(k, \text{NewBeam})$ 7 return $G = (\{0, 1, \ldots, n\}, A_{\text{Top}(1, \text{Beam})})$

Note:

- Score $(c_0,\ldots,c_m) = \sum_{i=1}^m \mathbf{w} \cdot \mathbf{f}(c_{i-1},t_i)$
- Simple combination of locally normalized classifier scores
- Marginal gains in accuracy



Structured Prediction

Parsing as structured prediction [Zhang and Clark 2008]:

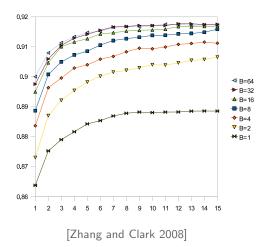
- Minimize loss over entire transition sequence
- Use beam search to find highest-scoring sequence
- ► Factored feature representations:

$$\mathbf{f}(c_0,\ldots,c_m)=\sum_{i=1}^m\mathbf{f}(c_{i-1},t_i)$$

- Online learning from oracle transition sequences:
 - Structured perceptron [Collins 2002]
 - Early update [Collins and Roark 2004]
 - Max-violation update [Huang et al. 2012]



Beam Size and Training Iterations



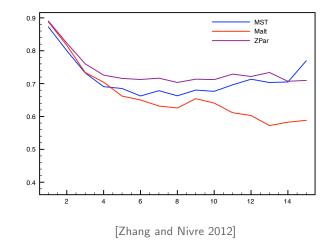
The Best of Two Worlds?

Like graph-based dependency parsing (MSTParser):

- Global learning minimize loss over entire sentence
- Non-greedy search accuracy increases with beam size
- Like (old school) transition-based parsing (MaltParser):
 - Highly efficient complexity still linear for fixed beam size
 - Rich features no constraints from parsing algorithm



Precision by Dependency Length





Even Richer Feature Models

	ZPar	Malt
Baseline	92.18	89.37
+distance	+0.07	-0.14
+valency	+0.24	0.00
+unigrams	+0.40	-0.29
+third-order	+0.18	0.00
+label set	+0.07	+0.06
Extended	93.14	89.00

[Zhang and Nivre 2011, Zhang and Nivre 2012]

 Adding graph-based features may require special techniques [Zhang and Clark 2008, Bohnet and Kuhn 2012]



The Need for Speed

- Beam search helps but slows down the parser
- What can we do to maintain the highest speed?
 - Easy-first parsing give up left-to-right incremental search
 - Dynamic oracles learn how to recover from errors
- These two ideas can be combined



Easy-First Non-Directional Parsing

 Process dependencies from easy to hard (not left to right) and from local to global (bottom up) [Goldberg and Elhadad 2010]

Configuration:(L, A)[L = List, A = Arcs]Initial: $([0, 1, \dots, n], \{ \})$ Terminal:([0], A)

 $\begin{array}{l} \text{Attach-Right}(i, k):\\ ([v_1, \dots, v_m], A) \ \Rightarrow \ ([v_1, \dots, v_{i-1}, v_{i+1}, \dots, v_m], A \cup \{(v_{i+1}, v_i, k)\})\\ \text{Attach-Left}(i, k):\\ ([v_1, \dots, v_m], A) \ \Rightarrow \ ([v_1, \dots, v_i, v_{i+2}, \dots, v_m], A \cup \{(v_i, v_{i+1}, k)\}) \end{array}$



Parsing Algorithm

Given an oracle o that selects the highest-confidence transition o(c), parsing is deterministic:

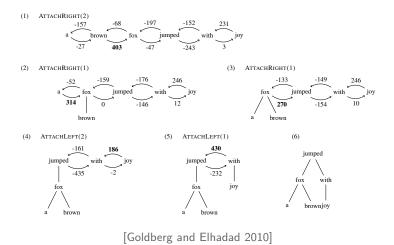
Parse
$$(w_1, ..., w_n)$$

1 $c \leftarrow ([0, 1, ..., n], \{ \})$
2 while length $(L_c) > 1$
3 $t \leftarrow o(c)$
4 $c \leftarrow t(c)$
5 return $G = (\{0, 1, ..., n\}, A_c)$

- Number of possible transitions grows with sentence length
- ▶ Parsing in *O*(*n* log *n*) time with priority heap



Parsing Example





Oracles Revisited

- How do we train the easy-first parser?
- Recall our training procedure for greedy parsers:
 - Reconstruct oracle transition sequence for each sentence
 - Construct training data set $D = \{(c, t) | o(c) = t\}$
 - Maximize accuracy of local predictions o(c) = t
- Presupposes a unique optimal transition for each configuration
 - Does not make sense for the easy-first parser
 - Turns out to be a bad idea in general



Online Learning with a Conventional Oracle

Learn($\{T_1, \ldots, T_N\}$) 1 $\mathbf{w} \leftarrow 0.0$ 2 for *i* in 1..K 3 for *j* in 1..*N* 4 $c \leftarrow ([], [0, 1, \ldots, n_i], \{\})$ 5 while $B_c \neq []$ 6 $t^* \leftarrow \operatorname{argmax}_t \mathbf{w} \cdot \mathbf{f}(c, t)$ 7 $t_o \leftarrow o(c, T_i)$ if $t^* \neq t_o$ 8 $\mathbf{w} \leftarrow \mathbf{w} + \mathbf{f}(c, t_o) - \mathbf{f}(c, t^*)$ 9 $c \leftarrow t_{o}(c)$ 10 11 return w



Online Learning with a Conventional Oracle

Learn($\{T_1, \ldots, T_N\}$) 1 $\mathbf{w} \leftarrow 0.0$ 2 for *i* in 1..K 3 for *j* in 1..*N* 4 $c \leftarrow ([], [0, 1, \ldots, n_i], \{\})$ 5 while $B_c \neq []$ 6 $t^* \leftarrow \operatorname{argmax}_t \mathbf{w} \cdot \mathbf{f}(c, t)$ 7 $t_o \leftarrow o(c, T_i)$ if $t^* \neq t_0$ 8 $\mathbf{w} \leftarrow \mathbf{w} + \mathbf{f}(c, \underline{t}_{o}) - \mathbf{f}(c, t^{*})$ 9 $c \leftarrow t_o(c)$ 10 11 return w

• Oracle $o(c, T_i)$ returns the optimal transition for c and T_i



Conventional Oracle for Arc-Eager Parsing

$$o(c, T) = \begin{cases} \text{Left-Arc} & \text{if } \text{top}(S_c) \leftarrow \text{first}(B_c) \text{ in } T\\ \text{Right-Arc} & \text{if } \text{top}(S_c) \rightarrow \text{first}(B_c) \text{ in } T\\ \text{Reduce} & \text{if } \exists v < \text{top}(S_c) : v \leftrightarrow \text{first}(B_c) \text{ in } T\\ \text{Shift} & \text{otherwise} \end{cases}$$

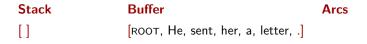
Correct:

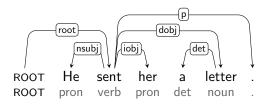
• Derives T in a configuration sequence $C_{o,T} = c_0, \ldots, c_m$

- Problems:
 - Deterministic: Ignores other derivations of T
 - Incomplete: Valid only for configurations in $C_{o,T}$



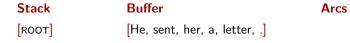
Transitions:

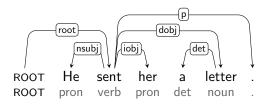






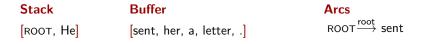


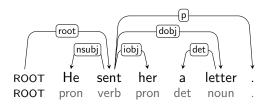






Transitions: SH-RA







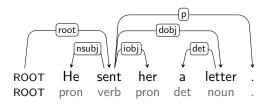




Buffer

[sent, her, a, letter, .]

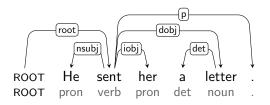






Transitions: SH-RA-LA-SH

Stack [ROOT, sent] Buffer [her, a, letter, .] Arcs ROOT $\xrightarrow{\text{root}}$ sent He $\xleftarrow{\text{sbj}}$ sent

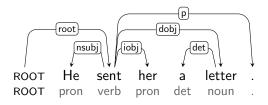




Transitions: SH-RA-LA-SH-RA

Stack Buffer [ROOT, sent, her] [a, letter, .]

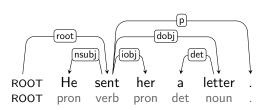






Transitions: SH-RA-LA-SH-RA-SH

Stack Buffer [ROOT, sent, her, a] [letter, .]

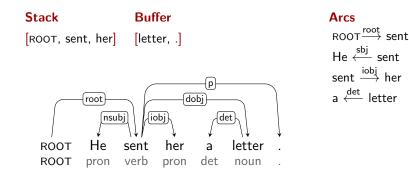


Arcs

 $\begin{array}{c} \mathsf{ROOT} \xrightarrow{\mathsf{root}} \mathsf{sent} \\ \mathsf{He} \xleftarrow{\mathsf{sbj}} \mathsf{sent} \\ \mathsf{sent} \xrightarrow{\mathsf{iobj}} \mathsf{her} \end{array}$

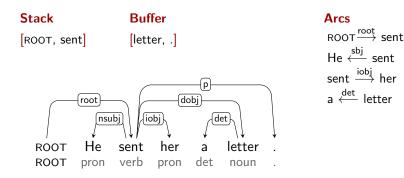


Transitions: SH-RA-LA-SH-RA-SH-LA





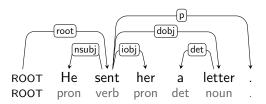
Transitions: SH-RA-LA-SH-RA-SH-LA-RE





Transitions: SH-RA-LA-SH-RA-SH-LA-RE-RA

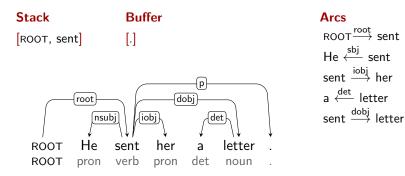
Stack Buffer [ROOT, sent, letter] [.]



Arcs ROOT $\xrightarrow{\text{root}}$ sent He $\xleftarrow{\text{sbj}}$ sent sent $\xrightarrow{\text{iobj}}$ her a $\xleftarrow{\text{det}}$ letter sent $\xrightarrow{\text{dobj}}$ letter

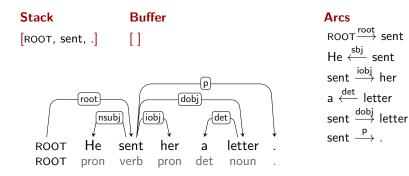


Transitions: SH-RA-LA-SH-RA-SH-LA-RE-RA-RE





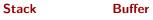
Transitions: SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA



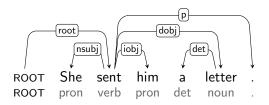


Transitions:

SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA SH-RA-LA-SH-RA



[ROOT, sent, her] [a, letter, .]



Arcs ROOT $\xrightarrow{\text{root}}$ sent He $\xleftarrow{\text{sbj}}$ sent sent $\xrightarrow{\text{iobj}}$ her



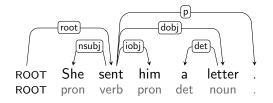
SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA SH-RA-LA-SH-RA-<mark>RE</mark>

Stack [ROOT, sent]

Transitions:

Buffer [a, letter, .]







Transitions:

ROOT, sent, a

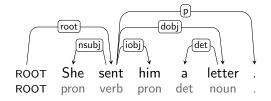
SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA SH-RA-LA-SH-RA-RE-SH

Stack Buffer

[letter, .]

Arcs

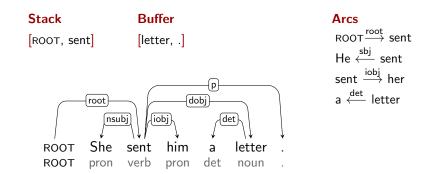
 $\begin{array}{c} \mathsf{ROOT} \xrightarrow{\mathsf{root}} \mathsf{sent} \\ \mathsf{He} \xleftarrow{\mathsf{sbj}} \mathsf{sent} \\ \mathsf{sent} \xrightarrow{\mathsf{iobj}} \mathsf{her} \end{array}$





Transitions:

SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA SH-RA-LA-SH-RA-<mark>RE-SH-LA</mark>



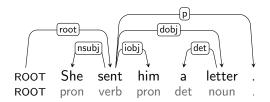


SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA SH-RA-LA-SH-RA-<mark>RE-SH-LA</mark>-RA

Stack Buffer

[ROOT, sent, letter] [.]

Transitions:

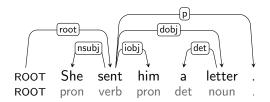


Arcs ROOT $\xrightarrow{\text{root}}$ sent He $\xleftarrow{\text{sbj}}$ sent sent $\xrightarrow{\text{iobj}}$ her a $\xleftarrow{\text{det}}$ letter sent $\xrightarrow{\text{dobj}}$ letter



Transitions: SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA SH-RA-LA-SH-RA-RE-SH-LA-RA-RE





Arcs ROOT $\xrightarrow{\text{root}}$ sent He $\xleftarrow{\text{sbj}}$ sent sent $\xrightarrow{\text{iobj}}$ her a $\xleftarrow{\text{det}}$ letter sent $\xrightarrow{\text{dobj}}$ letter



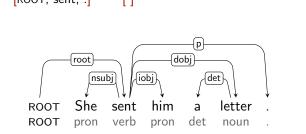
Non-Determinisim

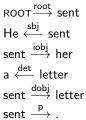
Transitions:

SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA SH-RA-LA-SH-RA-<mark>RE-SH-LA</mark>-RA-RE-RA

Stack		Buffer
ROOT sent	1	[]









SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA

Transitions: SH-RA-LA-SH

Stack

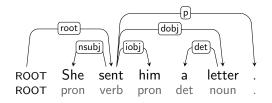
Buffer

[ROOT, sent]

[her, a, letter, .]

Arcs







SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA

Transitions: SH-RA-LA-SH-SH

Stack

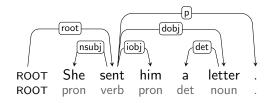
Buffer

Arcs

[ROOT, sent, her]

[a, letter, .]

 $\begin{array}{l} \mathsf{ROOT} \stackrel{root}{\longrightarrow} \mathsf{sent} \\ \mathsf{He} \xleftarrow{\mathsf{sbj}} \mathsf{sent} \end{array}$





SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA

Transitions: SH-RA-LA-SH-SH-SH

Stack

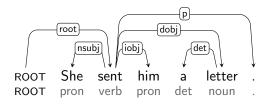
Buffer

Arcs

[ROOT, sent, her, a]









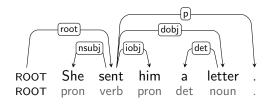
SH-RA-LA-SH-RA-SH-LA-RE-RA-Transitions: SH-RA-LA-SH-SH-LA

Stack

Buffer [letter, .]

Arcs

 $\begin{array}{c} \text{ROOT} \xrightarrow{\text{root}} \text{ sent} \\ \text{He} \xleftarrow{\text{sbj}} \text{ sent} \\ \text{a} \xleftarrow{\text{det}} \text{ letter} \end{array}$



ROOT, sent, her



SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA

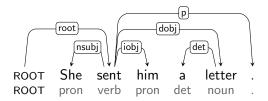
Transitions: SH-RA-LA-SH-SH-SH-LA-SH

Stack

Buffer

[]

[ROOT, sent, her, letter]



Arcs





SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA Transitions: SH-RA-LA-SH-SH-LA-SH-SH [3/6]

Stack

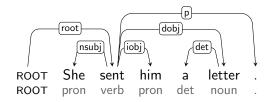
Buffer

[ROOT, sent, letter, .]

[]

Arcs





SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA Transitions: SH-RA-LA-SH-SH-SH-LA-SH-SH [3/6] SH-RA-LA-SH-SH-SH-LA



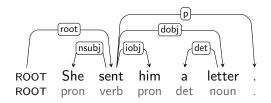
Buffer

[ROOT, sent, her]

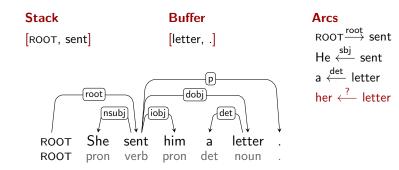
[letter, .]







SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA Transitions: SH-RA-LA-SH-SH-SH-LA-SH-SH [3/6] SH-RA-LA-SH-SH-SH-LA-LA



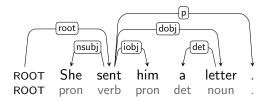
SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA Transitions: SH-RA-LA-SH-SH-SH-LA-SH-SH [3/6] SH-RA-LA-SH-SH-SH-LA-LA-RA



Buffer

[ROOT, sent, letter]



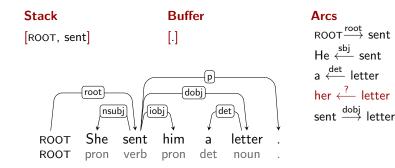


Arcs

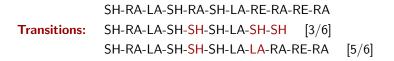




SH-RA-LA-SH-RA-SH-LA-RE-RA-RE-RA Transitions: SH-RA-LA-SH-SH-SH-LA-SH-SH [3/6] SH-RA-LA-SH-SH-SH-LA-LA-RA-RE





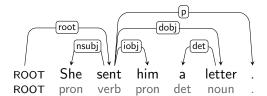




Buffer

[ROOT, sent, .]





Arcs





Dynamic Oracles

- Optimality:
 - A transition is optimal if the best tree remains reachable
 - Best tree = $\operatorname{argmin}_{T'} \mathcal{L}(T, T')$
- Oracle:
 - Boolean function o(c, t, T) =true if t is optimal for c and T
 - Non-deterministic: More than one transition can be optimal
 - Complete: Correct for all configurations
- New problem:
 - How do we know which trees are reachable?



Reachability for Arcs and Trees

- Arc reachability:
 - An arc w_i → w_j is reachable in c iff w_i → w_j ∈ A_c, or w_i ∈ S_c ∪ B_c and w_j ∈ B_c (same for w_i ← w_j)
- Tree reachability:
 - ► A (projective) tree *T* is reachable in *c* iff every arc in *T* is reachable in *c*
- Arc-decomposable systems [Goldberg and Nivre 2013]:
 - Tree reachability reduces to arc reachability
 - Holds for some transition systems but not all
 - Arc-eager and easy-first are arc-decomposable
 - Arc-standard is not decomposable



Oracles for Arc-Decomposable Systems

$$o(c, t, T) = \begin{cases} \text{true} & \text{if } [\mathcal{R}(c) - \mathcal{R}(t(c))] \cap T = \emptyset \\ \text{false} & \text{otherwise} \end{cases}$$
where $\mathcal{R}(c) \equiv \{a \mid a \text{ is an arc reachable in } c\}$

$$\frac{\text{Arc-Eager}}{\text{arce constants}}$$

$$o(c, \text{LA}, T) = \begin{cases} \text{false} & \text{if } \exists w \in B_c : s \leftrightarrow w \in T \text{ (except } s \leftarrow b) \\ \text{true} & \text{otherwise} \end{cases}$$

$$o(c, \text{RA}, T) = \begin{cases} \text{false} & \text{if } \exists w \in S_c : w \leftrightarrow b \in T \text{ (except } s \rightarrow b) \\ \text{true} & \text{otherwise} \end{cases}$$

$$o(c, \text{RE}, T) = \begin{cases} \text{false} & \text{if } \exists w \in B_c : s \rightarrow w \in T \\ \text{true} & \text{otherwise} \end{cases}$$

$$o(c, \text{SH}, T) = \begin{cases} \text{false} & \text{if } \exists w \in S_c : w \leftrightarrow b \in T \\ \text{true} & \text{otherwise} \end{cases}$$

$$O(c, \text{SH}, T) = \begin{cases} \text{false} & \text{if } \exists w \in S_c : w \leftrightarrow b \in T \\ \text{true} & \text{otherwise} \end{cases}$$

b = first node in the buffer B



Online Learning with a Dynamic Oracle

```
Learn(\{T_1, \ldots, T_N\})
  1
       \mathbf{w} \leftarrow 0.0
  2
       for i in 1..K
  3
                 for j in 1..N
                         c \leftarrow ([]_{S}, [w_1, \ldots, w_{n_i}]_B, \{\})
  4
  5
                         while B_c \neq []
                                 t^* \leftarrow \operatorname{argmax}_t \mathbf{w} \cdot \mathbf{f}(c, t)
  6
   7
                                 t_o \leftarrow \operatorname{argmax}_{t \in \{t \mid o(c,t,T_i)\}} \mathbf{w} \cdot \mathbf{f}(c,t)
  8
                                if t^* \neq t_o
                                        \mathbf{w} \leftarrow \mathbf{w} + \mathbf{f}(c, t_o) - \mathbf{f}(c, t^*)
  9
                                 c \leftarrow \text{choice}(t_o(c), t^*(c))
10
11
         return w
```

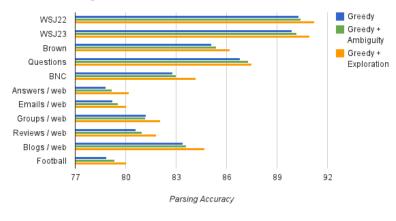


Online Learning with a Dynamic Oracle

```
Learn(\{T_1, \ldots, T_N\})
  1
       \mathbf{w} \leftarrow 0.0
  2
       for i in 1..K
  3
                  for i in 1...N
                         c \leftarrow ([]_{S}, [w_1, \ldots, w_{n_i}]_B, \{\})
  4
  5
                         while B_c \neq []
  6
                                 t^* \leftarrow \operatorname{argmax}_t \mathbf{w} \cdot \mathbf{f}(c, t)
   7
                                 t_o \leftarrow \operatorname{argmax}_{t \in \{t \mid o(c,t,T_i)\}} \mathbf{w} \cdot \mathbf{f}(c,t)
  8
                                if t^* \neq t_0
                                        \mathbf{w} \leftarrow \mathbf{w} + \mathbf{f}(c, t_o) - \mathbf{f}(c, t^*)
  9
                                 c \leftarrow \text{choice}(t_o(c), t^*(c))
10
11
          return w
```

- Ambiguity: use model score to break ties
- Exploration: follow model prediction even if not optimal





English Results

[Goldberg and Nivre 2012]



Ambiguity and Exploration

- Lessons from dynamic oracles:
 - ▶ Do not hide spurious ambiguity from the parser exploit it
 - Let the parser explore the consequences of its own mistakes
- Related work:
 - Bootstrapping [Choi and Palmer 2011]
 - Selectional branching [Choi and McCallum 2013]
 - ▶ Non-monotonic parsing [Honnibal et al. 2013]
 - Dynamic parsing strategy [Sartorio et al. 2013]



Non-Projective Parsing

- So far only projective parsing models
- ► Non-projective parsing harder even with greedy inference
 - ▶ Non-projective: n(n-1) arcs to consider $-O(n^2)$
 - Projective: at most 2(n-1) arcs to consider O(n)
- Also harder to construct dynamic oracles
 - Conjecture: arc-decomposability presupposes projectivity



Previous Approaches

- Pseudo-projective parsing [Nivre and Nilsson 2005]
 - Preprocess training data, post-process parser output
 - Approximate encoding with incomplete coverage
 - Relatively high precision but low recall
- Extended arc transitions [Attardi 2006]
 - Transitions that add arcs between non-adjacent subtrees
 - Upper bound on arc degree (limited to local relations)
 - Exact dynamic programming algorithm [Cohen et al. 2011]
- List-based algorithms [Covington 2001, Nivre 2007]
 - Consider all word pairs instead of adjacent subtrees
 - Increases parsing complexity (and training time)
 - Improved accuracy and efficiency by adding "projective transitions" [Choi and Palmer 2011]

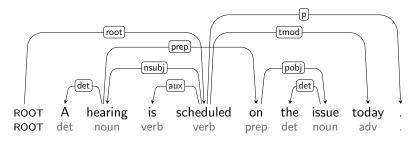


Novel Approaches

- Online reordering [Nivre 2009, Nivre et al. 2009]:
 - Reorder words during parsing to make tree projective
 - Add a special transition for swapping adjacent words
 - Quadratic time in the worst case but linear in the best case
- Multiplanar parsing [Gómez-Rodríguez and Nivre 2010]:
 - ▶ Factor dependency trees into *k* planes without crossing arcs
 - ▶ Use *k* stacks to parse each plane separately
 - Linear time parsing with constant k

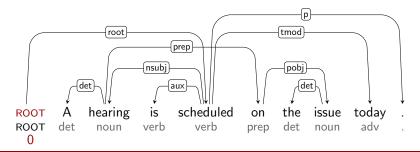


- Projectivity is a property of a dependency tree only in relation to a particular word order
 - ▶ Words can always be reordered to make the tree projective
 - ► Given a dependency tree T = (V, A, <), let the projective order <_p be the order defined by an inorder traversal of T with respect to < [Veselá et al. 2004]</p>



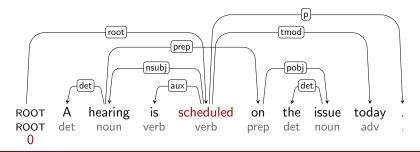


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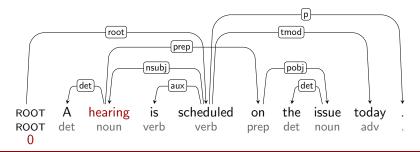


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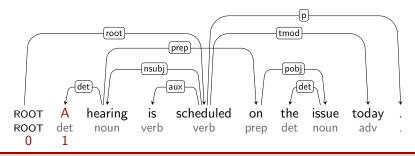


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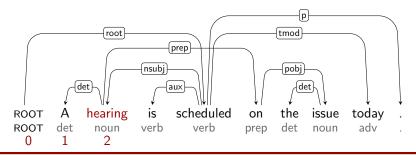


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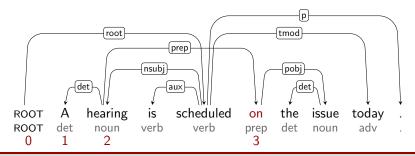


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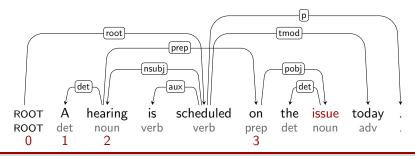


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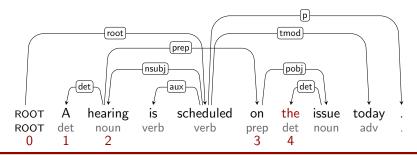


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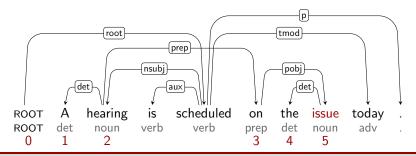


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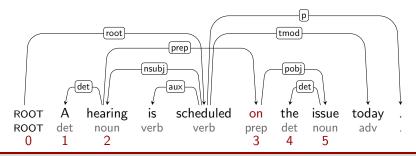


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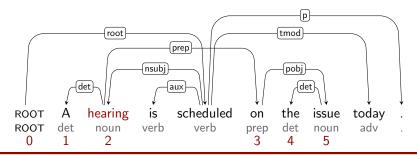


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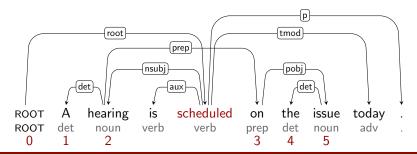


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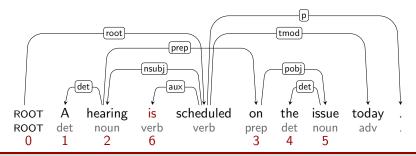


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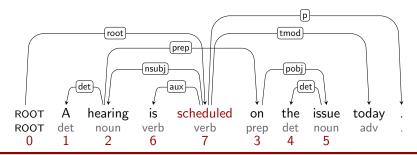


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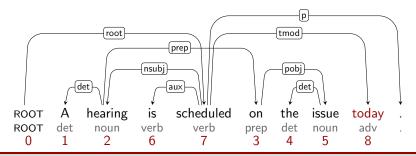


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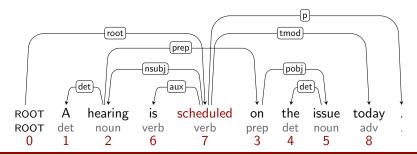


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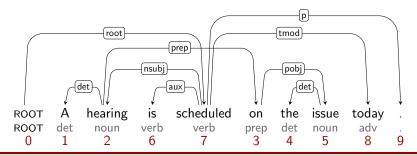


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Transition System for Online Reordering

Configuration:	(S, B, A) $[S = Stack, B = Buffer, A = Arcs]$						
Initial:	$([], [0, 1, \ldots, n], \{ \})$						
Terminal:	([0],[],A)						
Shift:	$(S, i B, A) \Rightarrow$	(S i, B, A)					
Right-Arc(k):	$(S i j, B, A) \Rightarrow$	$(S i,B,A\cup\{(i,j,k)\})$					
Left-Arc(k):	$(S i j, B, A) \Rightarrow$	$(S j, B, A \cup \{(j, i, k)\})$ $i \neq 0$					
Swap:	$(S i j, B, A) \Rightarrow$	(S j,i B,A) $0 < i < j$					



Transition System for Online Reordering

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Left-Arc(k):	$(S i j, B, A) \Rightarrow (S j, B, A \cup \{(j, i, k)\}) i \neq 0$						
Swap:	$(S i j, B, A) \Rightarrow (S j, i B, A) 0 < i < j$						

- Transition-based parsing with two interleaved processes:
 - 1. Sort words into projective order $<_p$
 - 2. Build tree T by connecting adjacent subtrees
- ► T is projective with respect to <_p but not (necessarily) <</p>



 $[]_S$ [ROOT, A, hearing, is, scheduled, on, the, issue, today, $.]_B$

hearing is scheduled today ROOT А the issue on det verb verb det adv ROOT noun prep noun



[ROOT]_S [A, hearing, is, scheduled, on, the, issue, today, $]_B$

hearing is scheduled today ROOT А the issue on det verb verb det adv ROOT noun prep noun



[ROOT, A]_S [hearing, is, scheduled, on, the, issue, today, .]_B

hearing is scheduled today ROOT А the issue on det verb verb det adv ROOT noun prep noun

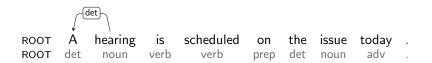


[ROOT, A, hearing]_S [is, scheduled, on, the, issue, today, .]_B

hearing is scheduled today ROOT Α the issue on det verb verb det adv ROOT noun prep noun

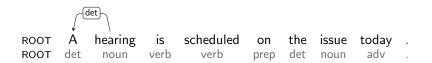


[ROOT, hearing]_S [is, scheduled, on, the, issue, today, $.]_B$



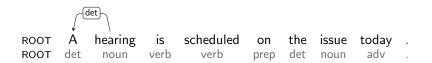


[ROOT, hearing, is]_S [scheduled, on, the, issue, today, .]_B





[ROOT, hearing, is, scheduled]_S [on, the, issue, today, $.]_B$





[ROOT, hearing, scheduled]_S [on, the, issue, today, .]_B





[ROOT, hearing, scheduled, on]_S [the, issue, today, .]_B





[ROOT, hearing, scheduled, on, the]_S [issue, today, .]_B





[ROOT, hearing, scheduled, on, the, issue]_S [today, .]_B





[ROOT, hearing, scheduled, on, issue]_S [today, .]_B

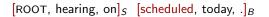


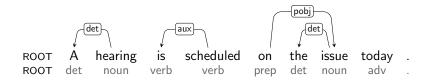


[ROOT, hearing, scheduled, on]_S [today, .]_B



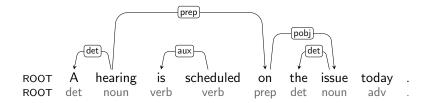






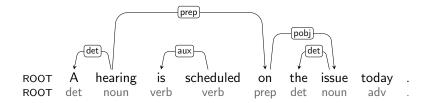


[ROOT, hearing]_S [scheduled, today, .]_B



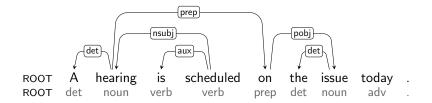


[ROOT, hearing, scheduled]_S [today, .]_B



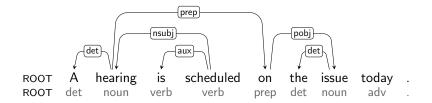


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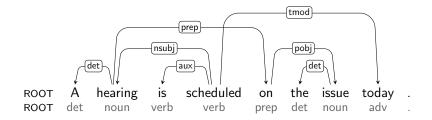


[ROOT, scheduled, today]_S [.]_B



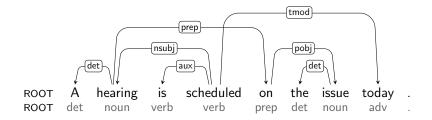


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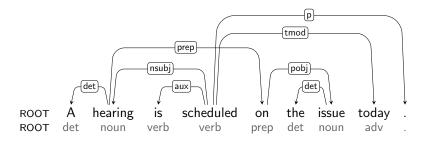


[ROOT, scheduled, .]_S []_B



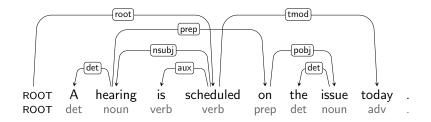


[ROOT, scheduled]_S []_B





[ROOT]*S* []*B*





Analysis

- Correctness:
 - Sound and complete for the class of non-projective trees
- Complexity for greedy or beam search parsing:
 - Quadratic running time in the worst case
 - Linear running time in the average case
- Works well with beam search and structured prediction

			German		
	LAS	UAS	LAS	UAS	
Projective				88.5	
Reordering	83.9	89.1	88.7	90.9	

[Bohnet and Nivre 2012]



Morphology and Syntax

- Morphological analysis in dependency parsing:
 - Crucially assumed as input, not predicted by the parser
 - Pipeline approach may lead to error propagation
 - Most PCFG-based parsers at least predict their own tags
- Recent interest in joint models for morphology and syntax:
 - ▶ Graph-based [McDonald 2006, Lee et al. 2011, Li et al. 2011]
 - ▶ Transition-based [Hatori et al. 2011, Bohnet and Nivre 2012]
- Can improve both morphology and syntax



Transition System for Morphology and Syntax

Configuration:	(S, B, M, A) [M = Morphology]					
Initial:	$([], [0, 1, \ldots, n], \{ \}, \{ \})$					
Terminal:	([0], [], <i>M</i> , <i>A</i>)					
Shift(p):	$(S, i B, M, A) \Rightarrow$	$(S i, B, M \cup \{(i, m)\}, A)$				
Right-Arc(k):	$(S i j, B, M, A) \Rightarrow$	$(S i,B,M,A\cup\{(i,j,k)\})$				
Left-Arc(k):	$(S i j, B, M, A) \Rightarrow$	$(S j, B, M, A \cup \{(j, i, k)\})$ $i \neq 0$				
Swap:	$(S i j, B, M, A) \Rightarrow$	(S j,i B,M,A) $0 < i < j$				



Transition System for Morphology and Syntax

Configuration:	(S, B, M, A) $[M = Morphology]$						
Initial:	$([], [0, 1, \ldots, n], \{ \}, \{ \}$	$([], [0, 1, \dots, n], \{ \}, \{ \})$					
Terminal:	([0], [], <i>M</i> , <i>A</i>)						
Shift(p):	$(S,i B,M,A) \Rightarrow (A)$	$S i, B, M \cup \{(i, m)\}, A\}$					
Right-Arc(k):	$(S i j, B, M, A) \Rightarrow (A)$	$S i, B, M, A \cup \{(i, j, k)\})$					
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Swap:	$(S i j, B, M, A) \Rightarrow (A)$	S j,i B,M,A) $0 < i < j$					

- Transition-based parsing with three interleaved processes:
 - Assign morphology when words are shifted onto the stack
 - Optionally sort words into projective order <_p
 - Build dependency tree T by connecting adjacent subtrees



Parsing Richly Inflected Languages

- ► Full morphological analysis: lemma + postag + features
 - Beam search and structured predication
 - Parser selects from k best tags + features
 - Rule-based morphology provides additional features
- Evaluation metrics:
 - PM = morphology (postag + features)
 - LAS = labeled attachment score

	Czech		Finnish		German		Hungarian		Russian	
	РМ	LAS	РM	LAS	PM	LAS	РМ	LAS	ΡМ	LAS
Pipeline										
Joint	94.4	83.5	91.6	82.5	91.2	92.1	97.4	89.1	95.1	88.0

[Bohnet et al. 2013]



Coming Up Next

- 1. Basic notions of dependency grammar and dependency parsing
- 2. Graph-based and transition-based dependency parsing
- 3. Advanced graph-based parsing techniques
- 4. Advanced transition-based parsing techniques
- 5. Neural network techniques in dependency parsing
- 6. Multilingual parsing from raw text to universal dependencies



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