

Deformations, cohomologies and homotopy of relative Rota-Baxter Lie algebras

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Rota-Baxter operators on Lie algebras

The notion of Rota-Baxter operators on Lie algebras was introduced as the operator form of the classical Yang-Baxter equation.

Definition

A linear operator $T : \mathfrak{g} \rightarrow \mathfrak{g}$ on a Lie algebra \mathfrak{g} is called a *Rota-Baxter operator* (of weight λ) if the following condition is satisfied:

$$[T(x), T(y)]_{\mathfrak{g}} = T([T(x), y]_{\mathfrak{g}} + [x, T(y)]_{\mathfrak{g}} + \lambda[x, y]_{\mathfrak{g}}).$$

Semonov-Tian-Shansky proved that if there is an ad-invariant, non-degenerate, symmetric bilinear form on \mathfrak{g} , then a Rota-Baxter operator and a *triangular r -matrix* ($[r, r] = 0$) are equivalent.

Example

Let the Lie algebra \mathfrak{g} be the direct sum of two subalgebras \mathfrak{g}_1 and \mathfrak{g}_2 . Then

$$T(x_1, x_2) = -x_1, \quad \forall x_1 \in \mathfrak{g}_1, x_2 \in \mathfrak{g}_2$$

is a Rota-Baxter operator of weight 1.

Modified Yang-Baxter equations

Let $R \in \text{End}(\mathfrak{g})$ be a solution of the **modified Yang-Baxter equation**:

$$[R(u), R(v)]_{\mathfrak{g}} = R([R(u), v]_{\mathfrak{g}}) + R([u, R(v)]_{\mathfrak{g}}) - [u, v]_{\mathfrak{g}},$$

from which Semenov-Tian-Shansky obtained an Infinitesimal Factorization Theorem for the Lie algebra \mathfrak{g} with important applications to integrable systems. Under the transformation

$$R = \text{Id} + 2T,$$

the operator R satisfies the modified Yang-Baxter equation if and only if the operator T is a Rota-Baxter operator of weight 1.

Relative Rota-Baxter operators on Lie algebras

Kupershmidt introduced the notion of a relative Rota-Baxter operator (also called an \mathcal{O} -operator) on a Lie algebra \mathfrak{g} with respect to arbitrary representation.

Definition

A *relative Rota-Baxter operator* on a Lie algebra $(\mathfrak{g}, [-, -]_{\mathfrak{g}})$ with respect to a representation $(V; \rho)$ is a linear map $T : V \rightarrow \mathfrak{g}$ satisfying the following quadratic constraint:

$$[Tu, Tv]_{\mathfrak{g}} = T(\rho(Tu)(v) - \rho(Tv)(u)), \quad \forall u, v \in V.$$

A *relative Rota-Baxter Lie algebra* is a triple $((\mathfrak{g}, [\cdot, \cdot]_{\mathfrak{g}}), \rho, T)$, where $(\mathfrak{g}, [\cdot, \cdot]_{\mathfrak{g}})$ is a Lie algebra, $\rho : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$ is a representation of \mathfrak{g} on a vector space V and $T : V \rightarrow \mathfrak{g}$ is a relative Rota-Baxter operator

Graph characterization of relative Rota-Baxter operators

Consider the semidirect product Lie algebra $(\mathfrak{g} \oplus V, [\cdot, \cdot]_{\ltimes})$:

$$[x + u, y + v]_{\ltimes} = [x, y]_{\mathfrak{g}} + \rho(x)v - \rho(y)u.$$

Proposition

A linear map $T : V \rightarrow \mathfrak{g}$ is a relative Rota-Baxter operator if and only if the graph of T ,

$$G_T := \{Tu + u \mid \forall u \in V\}$$

is a subalgebra of the semidirect product Lie algebra $(\mathfrak{g} \oplus V, [\cdot, \cdot]_{\ltimes})$.

Example

Let $r \in \wedge^2 \mathfrak{g}$ be a *triangular r -matrix*. Define $r^\sharp : \mathfrak{g}^* \rightarrow \mathfrak{g}$ by $\langle r^\sharp(\xi), \eta \rangle = r(\xi, \eta)$. Then r^\sharp is a relative RB operator on \mathfrak{g} with respect to the coadjoint representation.

It is well known that a triangular r -matrix gives rise to a triangular Lie bialgebra, which we denote by (\mathfrak{g}, r) . We will see that deformations and cohomologies of triangular Lie bialgebras can be studied using the general framework of relative Rota-Baxter Lie algebras.

Example

Let $\omega \in \wedge^2 \mathfrak{g}^*$ be a *symplectic structure* on a Lie algebra \mathfrak{g} . Then $(\omega^\sharp)^{-1}$ is a relative Rota-Baxter operator on the Lie algebra \mathfrak{g} with respect to the coadjoint representation, where $\omega^\sharp : \mathfrak{g} \rightarrow \mathfrak{g}^*$ is defined by $\langle \omega^\sharp(x), y \rangle = \omega(x, y)$ for $x, y \in \mathfrak{g}$.

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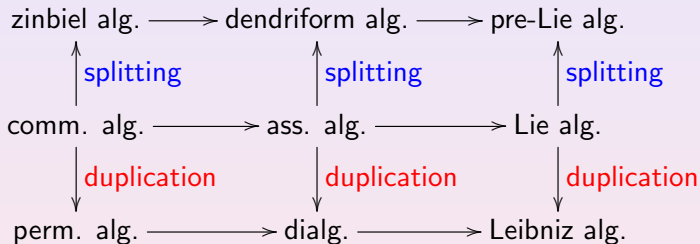
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Rota-Baxter operators \rightsquigarrow splitting of algebras



Averaging operators (embedding tensors) \rightsquigarrow duplication of algebras

Our approach to study deformations, cohomologies and homotopy of RB Lie algebras is using the ‘controlling algebra’.

More precisely, we construct an L_∞ -algebra whose Maurer-Cartan elements are relative Rota-Baxter Lie algebras.

- A relative Rota-Baxter Lie algebra gives rise to a twisted L_∞ -algebra that controls its deformations;
- The l_1 in the above twisted L_∞ -algebra defines a cohomology of the relative Rota-Baxter Lie algebra;
- Replace vector spaces by graded vector spaces, we get homotopy relative Rota-Baxter Lie algebras.

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- Replace vector spaces by graded vector spaces, we get homotopy relative Rota-Baxter Lie algebras.

Controlling algebra for Lie algebras

Let \mathfrak{g} be a vector space. The graded vector space

$$C^*(\mathfrak{g}, \mathfrak{g}) = \bigoplus_{n=0}^{+\infty} C^n(\mathfrak{g}, \mathfrak{g}) = \bigoplus_{n=0}^{+\infty} \text{Hom}(\wedge^{n+1} \mathfrak{g}, \mathfrak{g}).$$

equipped with the **Nijenhuis-Richardson bracket**

$$[P, Q]_{\text{NR}} = P \bar{\circ} Q - (-1)^{pq} Q \bar{\circ} P, \quad \forall P \in C^p(\mathfrak{g}, \mathfrak{g}), Q \in C^q(\mathfrak{g}, \mathfrak{g}),$$

is a **graded Lie algebra**, where $P \bar{\circ} Q \in C^{p+q}(\mathfrak{g}, \mathfrak{g})$ is defined by

$$(P \bar{\circ} Q)(x_1, \dots, x_{p+q+1}) = \sum_{\sigma \in \mathbb{S}_{(q+1, p)}} P(Q(x_{\sigma(1)}, \dots, x_{\sigma(q+1)}), x_{\sigma(q+2)}, \dots, x_{\sigma(p+q+1)})$$

Lemma

$\mu \in \text{Hom}(\wedge^2 \mathfrak{g}, \mathfrak{g})$ defines a Lie algebra structure on \mathfrak{g} if and only if

$$[\mu, \mu]_{\text{NR}} = 0.$$

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Lemma

$\mu \in \text{Hom}(\wedge^2 \mathfrak{g}, \mathfrak{g})$ defines a Lie algebra structure on \mathfrak{g} if and only if

$$[\mu, \mu]_{\text{NR}} = 0.$$

Define d_μ by $d_\mu = [\mu, \cdot]_{\text{NR}}$. Then $(C^*(\mathfrak{g}, \mathfrak{g}), [\cdot, \cdot]_{\text{NR}}, d_\mu)$ is a dgLa, that controls deformations of the Lie algebra (\mathfrak{g}, μ) .

Theorem

Let (\mathfrak{g}, μ) be a Lie algebra and $\mu' \in \text{Hom}(\wedge^2 \mathfrak{g}, \mathfrak{g})$. Then $(\mathfrak{g}, \mu + \mu')$ is a Lie algebra if and only if μ' is a Maurer-Cartan element of the dgLa $(C^(\mathfrak{g}, \mathfrak{g}), [\cdot, \cdot]_{\text{NR}}, d_\mu)$.*

Applications to cohomologies of Lie algebras

It is well known that the Chevalley-Eilenberg coboundary operator $d_{\text{CE}} : \text{Hom}(\wedge^k \mathfrak{g}, \mathfrak{g}) \rightarrow \text{Hom}(\wedge^{k+1} \mathfrak{g}, \mathfrak{g})$ for a Lie algebra \mathfrak{g} is given by

$$d_{\text{CE}} f(x_1, \dots, x_{k+1}) = \sum_{i=1}^k (-1)^{i+1} [x_i, f(x_1, \dots, \hat{x}_i, \dots, x_{k+1})] \\ + \sum_{i < j} (-1)^{i+j} f([x_i, x_j], x_1, \dots, \hat{x}_i, \dots, \hat{x}_j, \dots, x_{k+1}).$$

Theorem-Definition

Let (\mathfrak{g}, μ) be a Lie algebra. Then

$$d_{\text{CE}} f = (-1)^{k+1} [\mu, f]_{\text{NR}}, \quad \forall f \in \text{Hom}(\wedge^k \mathfrak{g}, \mathfrak{g}).$$

Let V be a \mathbb{Z} -graded vector space. Denote by $\text{Hom}^n(\text{Sym}(V), V)$ the space of degree n linear maps from the graded vector space $\text{Sym}(V) = \bigoplus_{i=1}^{+\infty} \text{Sym}^i(V)$ to the \mathbb{Z} -graded vector space V . Set $C^n(V, V) := \text{Hom}^n(\text{Sym}(V), V)$ and $C^*(V, V) := \bigoplus_{n \in \mathbb{Z}} C^n(V, V)$. Then we have the **graded Nijenhuis-Richardson bracket** $[\cdot, \cdot]_{\text{NR}}$ on the graded vector space $C^*(V, V)$, which is a graded Lie algebra.

Theorem-Definition

The Maurer-Cartan elements $\sum_{k=1}^{+\infty} l_k$ of the graded Lie algebra $(C^(V, V), [\cdot, \cdot]_{\text{NR}})$ are the L_∞ -algebra structures on V .*

The controlling algebras for other algebras

- The **gLa** structure for **associative algebras** is given by the Gerstenhaber bracket on $\oplus \text{Hom}(\otimes^k V, V)$. The cohomology groups for the deformation theories of associative algebras are the **Hochschild cohomology** groups;
- The **gLa** structure for **pre-Lie algebras (left-symmetric algebras)** is given by the Matsushima-Nijenhuis bracket on $\oplus \text{Hom}(\wedge^{k-1} V \otimes V, V)$. The cohomology groups for the deformation theories of pre-Lie algebras are the **Dzhumadil'daev cohomology** groups;
- The controlling algebra for Leibniz algebras is a **gLa**;
- The controlling algebra for n -Lie algebras is a **gLa**.

Definition

An L_∞ -algebra is a \mathbb{Z} -graded vector space $\mathfrak{g} = \bigoplus_{k \in \mathbb{Z}} \mathfrak{g}^k$ equipped with a collection ($k \geq 1$) of linear maps $l_k : \bigotimes^k \mathfrak{g} \rightarrow \mathfrak{g}$ of degree 1 with the property that, for any homogeneous elements $x_1, \dots, x_n \in \mathfrak{g}$, we have

(i) (graded symmetry) for every $\sigma \in \mathbb{S}_n$,

$$l_n(x_{\sigma(1)}, \dots, x_{\sigma(n-1)}, x_{\sigma(n)}) = \varepsilon(\sigma) l_n(x_1, \dots, x_{n-1}, x_n),$$

(ii) (generalized Jacobi identity) for all $n \geq 1$,

$$\sum_{i=1}^n \sum_{\sigma \in \mathbb{S}(i, n-i)} \varepsilon(\sigma) l_{n-i+1}(l_i(x_{\sigma(1)}, \dots, x_{\sigma(i)}), x_{\sigma(i+1)}, \dots, x_{\sigma(n)}) = 0.$$

Definition (Getzler)

The set of **Maurer-Cartan elements** of an L_∞ -algebra \mathfrak{g} is the set of those $\alpha \in \mathfrak{g}^0$ satisfying the Maurer-Cartan equation

$$\sum_{k=1}^{+\infty} \frac{1}{k!} l_k(\alpha, \dots, \alpha) = 0.$$



E. Getzler, Lie theory for nilpotent L_∞ -algebras. *Ann. Math.* (2) **170** (2009), 271-301.

Main results: the controlling algebra of relative Rota-Baxter Lie algebra

Let \mathfrak{g} and V be vector spaces. Denote by L' the following graded vector space

$$L' = \bigoplus_{n=0}^{+\infty} \text{Hom}(\wedge^{n+1} \mathfrak{g}, \mathfrak{g}) \oplus \text{Hom}(\wedge^n \mathfrak{g} \otimes V, V),$$

and denote by $\mathfrak{h} = \bigoplus_{n=0}^{+\infty} \text{Hom}(\wedge^{n+1} V, \mathfrak{g})$.

Theorem (Lazarev-S-Tang)

There is an L_∞ -algebra structure $\{l_k\}_{k=1}^{+\infty}$ on the graded vector space $L'[1] \oplus \mathfrak{h}$, such that its Maurer-Cartan elements are exactly relative Rota-Baxter Lie algebra structures on \mathfrak{g} and V .

Maurer-Cartan elements contains

$$\mu \in \text{Hom}(\wedge^2 \mathfrak{g}, \mathfrak{g}), \quad \rho \in \text{Hom}(\mathfrak{g} \otimes V, V), \quad T \in \text{Hom}(V, \mathfrak{g}).$$

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Deformations of relative Rota-Baxter Lie algebras

Let (μ, ρ, T) be a relative Rota-Baxter Lie algebra structure on \mathfrak{g} and V . Define $l_k^{\mu, \rho, T}$ by

$$l_k^{\mu, \rho, T}(x_1, \dots, x_k) = \sum_{n=0}^{+\infty} \frac{1}{n!} l_{k+n}(\underbrace{\mu + \rho + T, \dots, \mu + \rho + T}_n, x_1, \dots, x_k).$$

According to Getzler's results, $(L'[1] \oplus \mathfrak{h}, \{l_k^{\mu, \rho, T}\}_{k=1}^{+\infty})$ is an L_∞ -algebra, called **the twisted L_∞ -algebra**.

Theorem (Lazarev-S-Tang)

The triple $(\mu + \mu', \rho + \rho', T + T')$ is again a relative Rota-Baxter Lie algebra for

$$\mu' \in \text{Hom}(\wedge^2 \mathfrak{g}, \mathfrak{g}), \quad \rho' \in \text{Hom}(\mathfrak{g}, \mathfrak{gl}(V)), \quad T' \in \text{Hom}(V, \mathfrak{g}),$$

if and only if $\mu' + \rho' + T'$ is a Maurer-Cartan element of the L_∞ -algebra $(L'[1] \oplus \mathfrak{h}, \{l_k^{\mu, \rho, T}\}_{k=1}^{+\infty})$.

There is a well known slogan, often attributed to Deligne, Drinfeld and Kontsevich: *every reasonable deformation theory is controlled by a differential graded Lie algebra (an L_∞ -algebra), determined up to quasi-isomorphism.*

Related works in Poisson geometry

-  **F. Schatz and M. Zambon**, Deformations of pre-symplectic structures and the Koszul L_∞ -algebra. **IMRN** 2020.
-  **M. Gualtieri, M. Matviichuk and G. Scott**, Deformation of Dirac structures via L_∞ -algebras. **IMRN** 2020.
-  **Y. Frégier and M. Zambon**, Simultaneous deformations and Poisson geometry. **Compos. Math.** (2015).
-  **H. Le, Y. Oh, A. Tortorella and L. Vitagliano**, Deformations of coisotropic submanifolds in Jacobi manifolds. *J. Symplectic Geom.* (2018).
-  **Y. Frégier and M. Zambon**, Simultaneous deformations of algebras and morphisms via derived brackets. *JPAA* (2015).
-  **Y. Frégier, M. Markl and D. Yau**, The L_∞ -deformation complex of diagrams of algebras. *New York J. Math.* (2009).

Recall that $\mathfrak{h} = \bigoplus_{k=1}^{+\infty} \text{Hom}(\wedge^{n+1} V, \mathfrak{g})$ and

$$L' = \bigoplus_{n=0}^{+\infty} \text{Hom}(\wedge^{n+1} \mathfrak{g}, \mathfrak{g}) \oplus \text{Hom}(\wedge^n \mathfrak{g} \otimes V, V).$$

Theorem (Lazarev-S.-Tang)

Let $((\mathfrak{g}, \mu), \rho, T)$ be a relative Rota-Baxter Lie algebra. Then the L_∞ -algebra $(L'[1] \oplus \mathfrak{h}, \{l_k^{\mu, \rho, T}\}_{k=1}^{+\infty})$ is a **strict extension** of the L_∞ -algebra $(\text{dglA}) L'[1]$ by the L_∞ -algebra $(\text{dglA}) \mathfrak{h}$, that is, we have the following short exact sequence of L_∞ -algebras:

$$0 \longrightarrow \mathfrak{h} \xrightarrow{\iota} L'[1] \oplus \mathfrak{h} \xrightarrow{p} L'[1] \longrightarrow 0,$$

where $\iota(\theta) = (0, \theta)$ and $p(f, \theta) = f$.

Cohomology of relative Rota-Baxter Lie algebras

Let (μ, ρ, T) be a relative Rota-Baxter Lie algebra structure on \mathfrak{g} and V . Define the space of n -cochains $\mathfrak{C}^n(\mu, \rho, T)$ by

$$\left(\text{Hom}(\wedge^n \mathfrak{g}, \mathfrak{g}) \oplus \text{Hom}(\wedge^{n-1} \mathfrak{g} \otimes V, V) \right) \oplus \text{Hom}(\wedge^{n-1} V, \mathfrak{g}).$$

Define the **coboundary operator** $\mathcal{D} : \mathfrak{C}^n(\mu, \rho, T) \rightarrow \mathfrak{C}^{n+1}(\mu, \rho, T)$ by

$$\mathcal{D}(f, \theta) = (-1)^n l_1^{\mu, \rho, T}(f, \theta).$$

We obtain that $(\bigoplus_{n=0}^{+\infty} \mathfrak{C}^n(\mu, \rho, T), \mathcal{D})$ is a cochain complex.

Definition

*The cohomology of the cochain complex $(\bigoplus_{n=0}^{+\infty} \mathfrak{C}^n(\mu, \rho, T), \mathcal{D})$ is called the **cohomology of the relative Rota-Baxter Lie algebra**. We denote its n -th cohomology group by $\mathcal{H}^n(\mu, \rho, T)$*

Infinitesimal deformations

Consider infinitesimal deformations of a relative Rota-Baxter Lie algebra structure (μ, ρ, T) on \mathfrak{g} and V :

$$\begin{aligned}\mu_t &= \mu + t\mu' \\ \rho_t &= \rho + t\rho' \\ T_t &= T + tT'.\end{aligned}$$

Theorem

There is a one-to-one correspondence between equivalence classes of infinitesimal deformations of the relative Rota-Baxter Lie algebra $(\mathfrak{g}, \mu, \rho, T)$ and the second cohomology group $\mathcal{H}^2(\mu, \rho, T)$.

Relations among cohomologies

Denote by

$$\begin{aligned}\mathfrak{C}^n(\mu, \rho) &= \text{Hom}(\wedge^n \mathfrak{g}, \mathfrak{g}) \oplus \text{Hom}(\wedge^{n-1} \mathfrak{g} \otimes V, V), \\ \mathfrak{C}^n(T) &= \text{Hom}(\wedge^{n-1} V, \mathfrak{g}).\end{aligned}$$

The coboundary operator $\mathcal{D} : \mathfrak{C}^n(\mu, \rho, T) \rightarrow \mathfrak{C}^{n+1}(\mu, \rho, T)$ is given by

$$\begin{aligned}\mathcal{D}(f, \theta) &= (-1)^n (-[\pi, f]_{\text{NR}}, [[\pi, T]_{\text{NR}}, \theta]_{\text{NR}} + \frac{1}{n!} \underbrace{[\cdots [f, T]_{\text{NR}}, T]_{\text{NR}}, \cdots, T]_{\text{NR}}) \\ &= (\partial f, \delta \theta + h_T f).\end{aligned}$$

\mathcal{D} can be well-explained by the following diagram:

$$\begin{array}{ccccccc} \cdots & \longrightarrow & \mathfrak{C}^n(\mu, \rho) & \xrightarrow{\partial} & \mathfrak{C}^{n+1}(\mu, \rho) & \xrightarrow{\partial} & \mathfrak{C}^{n+2}(\mu, \rho) \longrightarrow \cdots \\ & & \searrow h_T & & \searrow h_T & & \\ \cdots & \longrightarrow & \mathfrak{C}^n(T) & \xrightarrow{\delta} & \mathfrak{C}^{n+1}(T) & \xrightarrow{\delta} & \mathfrak{C}^{n+2}(T) \longrightarrow \cdots \end{array}$$

Theorem (Lazarev-S.-Tang)

There is a *short exact sequence of the cochain complexes*:

$$0 \longrightarrow (\oplus_{n=0}^{+\infty} \mathfrak{C}^n(T), \delta) \xrightarrow{\iota} (\oplus_{n=0}^{+\infty} \mathfrak{C}^n(\mu, \rho, T), \mathcal{D}) \xrightarrow{p} (\oplus_{n=0}^{+\infty} \mathfrak{C}^n(\mu, \rho), \partial) \longrightarrow 0,$$

and there is a *long exact sequence of the cohomology groups*:

$$\cdots \longrightarrow \mathcal{H}^n(T) \xrightarrow{\mathcal{H}^n(\iota)} \mathcal{H}^n(\mu, \rho, T) \xrightarrow{\mathcal{H}^n(p)} \mathcal{H}^n(\mu, \rho) \xrightarrow{c^n} \mathcal{H}^{n+1}(T) \longrightarrow \cdots,$$

where the connecting map c^n is defined by $c^n([\alpha]) = [h_T \alpha]$, for all $[\alpha] \in \mathcal{H}^n(\mathfrak{g}, \rho)$.

Cohomology of RB Lie algebras

Let $(\mathfrak{g}, [\cdot, \cdot]_{\mathfrak{g}}, T)$ be a Rota-Baxter Lie algebra. Define the space of ***n-cochains*** $\mathfrak{C}_{\text{RB}}^n(\mathfrak{g}, T)$ by

$$\mathfrak{C}_{\text{RB}}^n(\mathfrak{g}, T) := \mathfrak{C}_{\text{Lie}}^n(\mathfrak{g}; \mathfrak{g}) \oplus \mathfrak{C}^n(T) = \text{Hom}(\wedge^n \mathfrak{g}, \mathfrak{g}) \oplus \text{Hom}(\wedge^{n-1} \mathfrak{g}, \mathfrak{g}).$$

Define $\mathcal{D}_{\text{RB}} : \mathfrak{C}_{\text{RB}}^n(\mathfrak{g}, T) \longrightarrow \mathfrak{C}_{\text{RB}}^{n+1}(\mathfrak{g}, T)$ by

$$\mathcal{D}_{\text{RB}}(f, \theta) = \left(d_{\text{CE}}f, \delta\theta + \Omega f \right), \quad \forall f \in \text{Hom}(\wedge^n \mathfrak{g}, \mathfrak{g}), \theta \in \text{Hom}(\wedge^{n-1} \mathfrak{g}, \mathfrak{g}),$$

where $\Omega : \text{Hom}(\wedge^n \mathfrak{g}, \mathfrak{g}) \longrightarrow \text{Hom}(\wedge^n \mathfrak{g}, \mathfrak{g})$ is defined by

$$\begin{aligned} (\Omega f)(x_1, \dots, x_n) &= (-1)^n \left(f(Tx_1, \dots, Tx_n) \right. \\ &\quad \left. - \sum_{i=1}^n Tf(Tx_1, \dots, Tx_{i-1}, x_i, Tx_{i+1}, \dots, Tx_n) \right). \end{aligned}$$

Theorem (Lazarev-S.-Tang)

The map \mathcal{D}_{RB} is a coboundary operator, i.e. $\mathcal{D}_{\text{RB}} \circ \mathcal{D}_{\text{RB}} = 0$.

Definition (Lazarev-S.-Tang)

Let $(\mathfrak{g}, [\cdot, \cdot]_{\mathfrak{g}}, T)$ be a Rota-Baxter Lie algebra. The cohomology of the cochain complex $(\oplus_{n=0}^{+\infty} \mathfrak{C}_{\text{RB}}^n(\mathfrak{g}, T), \mathcal{D}_{\text{RB}})$ is taken to be the **cohomology of the Rota-Baxter Lie algebra** $(\mathfrak{g}, [\cdot, \cdot]_{\mathfrak{g}}, T)$. Denote the n -th cohomology group by $\mathcal{H}_{\text{RB}}^n(\mathfrak{g}, T)$.

Cohomology of triangular Lie bialgebras

Let $(\mathfrak{g}, [\cdot, \cdot]_{\mathfrak{g}}, r)$ be a triangular Lie bialgebra. Define the space of n -cochains $\mathfrak{C}_{\text{TLB}}^n(\mathfrak{g}, r)$ by

$$\mathfrak{C}_{\text{TLB}}^n(\mathfrak{g}, r) := \text{Hom}(\wedge^n \mathfrak{g}, \mathfrak{g}) \oplus \wedge^n \mathfrak{g}.$$

Define the *coboundary operator* $\mathcal{D}_{\text{TLB}} : \mathfrak{C}_{\text{TLB}}^n(\mathfrak{g}, r) \rightarrow \mathfrak{C}_{\text{TLB}}^{n+1}(\mathfrak{g}, r)$ by

$$\mathcal{D}_{\text{TLB}}(f, \chi) = \left(d_{\text{CE}}f, d_r\chi + \Theta f \right), \quad \forall f \in \text{Hom}(\wedge^n \mathfrak{g}, \mathfrak{g}), \chi \in \wedge^n \mathfrak{g},$$

where $d_r : \wedge^n \mathfrak{g} \rightarrow \wedge^{n+1} \mathfrak{g}$ is given by $d_r\chi = [r, \chi]$ and

$\Theta : \text{Hom}(\wedge^n \mathfrak{g}, \mathfrak{g}) \rightarrow \wedge^{n+1} \mathfrak{g}$ is defined by

$$\langle \Theta f, \xi_1 \wedge \cdots \wedge \xi_{n+1} \rangle = \sum_{i=1}^{n+1} (-1)^{i+1} \langle \xi_i, f(r^\sharp(\xi_1), \dots, r^\sharp(\xi_{i-1}), r^\sharp(\xi_{i+1}), \dots, r^\sharp(\xi_{n+1})) \rangle.$$

Theorem (Lazarev-S.-Tang)

The map \mathcal{D}_{TLB} is a coboundary operator, i.e. $\mathcal{D}_{\text{TLB}} \circ \mathcal{D}_{\text{TLB}} = 0$.

Definition (Lazarev-S.-Tang)

Let $(\mathfrak{g}, [\cdot, \cdot]_{\mathfrak{g}}, r)$ be a triangular Lie bialgebra. The cohomology of the cochain complex $(\oplus_{n=0}^{+\infty} \mathfrak{C}_{\text{TLB}}^n(\mathfrak{g}, r), \mathcal{D}_{\text{TLB}})$ is called the **cohomology of the triangular Lie bialgebra** $(\mathfrak{g}, [\cdot, \cdot]_{\mathfrak{g}}, r)$. Denote the n -th cohomology group by $\mathcal{H}_{\text{TLB}}^n(\mathfrak{g}, r)$.

Homotopy relative Rota-Baxter Lie algebras

Let $(\mathfrak{g}, \{l_k\}_{k=1}^{+\infty})$ be an L_∞ -algebra and $(V, \{\rho_k\}_{k=1}^{+\infty})$ a representation. Then $(\mathfrak{h} := \bigoplus_{n \in \mathbb{Z}} \text{Hom}^n(\text{Sym}(V), \mathfrak{g}), \{l_k\}_{k=1}^{+\infty})$ is an L_∞ -algebra, where l_k is given by

$$l_k(a_1, \dots, a_k) = P \left[\underbrace{\dots}_{k} \left[\sum_{k=1}^{+\infty} (l_k + \rho_k), a_1 \right]_{\text{NR}}, a_2 \right]_{\text{NR}}, \dots, a_k \right]_{\text{NR}}.$$

Theorem-Definition (Lazarev-S.-Tang)

A degree 0 element $T = \sum_{k=1}^{+\infty} T_k \in \text{Hom}(\text{Sym}(V), \mathfrak{g})$ is a *homotopy relative Rota-Baxter operator* on $(\mathfrak{g}, \{l_k\}_{k=1}^{+\infty})$ with respect to the representation $(V, \{\rho_k\}_{k=1}^{+\infty})$ if and only if $T = \sum_{k=1}^{+\infty} T_k$ is a Maurer-Cartan element of the L_∞ -algebra $(\mathfrak{h}, \{l_k\}_{k=1}^{+\infty})$.

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Remark

Dotsenko and Khoroshkin studied the homotopy of Rota-Baxter operators on associative algebras in



*V. Dotsenko and A. Khoroshkin, Quillen homology for operads via Gröbner bases. Doc. Math. **18** (2013), 707-747.*

and noted that “in general compact formulas are yet to be found”. For Rota-Baxter Lie algebras, one encounters a similarly challenging situation.

We use the approach of ‘controlling algebras’ and their MC elements to formulate the notion of a homotopy version of a relative Rota-Baxter Lie algebra. Hopefully our research will provide some useful information for the operadic research of the homotopy of relative Rota-Baxter Lie algebras.

Explicit formula for a homotopy RB operator

A degree 0 element $T = \sum_{k=1}^{+\infty} T_k \in \text{Hom}(\text{Sym}(V), \mathfrak{g})$ with $T_k \in \text{Hom}(\text{Sym}^k(V), \mathfrak{g})$ is a homotopy relative Rota-Baxter operator on an L_∞ -algebra $(\mathfrak{g}, \{l_k\}_{k=1}^{+\infty})$ with respect to the representation $(V, \{\rho_k\}_{k=1}^{+\infty})$ if the following equalities hold for all $p \geq 1$ and all homogeneous elements $v_1, \dots, v_p \in V$,

$$\begin{aligned} & \sum_{\substack{k_1 + \dots + k_m = t \\ 1 \leq t \leq p-1}} \sum_{\sigma \in \mathbb{S}(k_1, \dots, k_m, 1, p-1-t)} \frac{\varepsilon(\sigma)}{m!} \cdot \\ & T_{p-t} \left(\rho_{m+1} \left(T_{k_1}(v_{\sigma(1)}, \dots, v_{\sigma(k_1)}), \dots, T_{k_m}(v_{\sigma(k_1+\dots+k_{m-1}+1)}, \dots, v_{\sigma(t)}), v_{\sigma(t+1)} \right), \right. \\ & \left. v_{\sigma(t+2)}, \dots, v_{\sigma(p)} \right) \\ = & \sum_{k_1 + \dots + k_n = p} \sum_{\sigma \in \mathbb{S}(k_1, \dots, k_n)} \frac{\varepsilon(\sigma)}{n!} l_n \left(T_{k_1}(v_{\sigma(1)}, \dots, v_{\sigma(k_1)}), \dots, T_{k_n}(v_{\sigma(k_1+\dots+k_{n-1}+1)}, \dots, v_{\sigma(p)}) \right). \end{aligned}$$



F. Chapoton and **M. Livernet**, Pre-Lie algebras and the rooted trees operad. **IMRN** **8** (2001), 395-408.

Definition

A *pre-Lie $_{\infty}$ -algebra* structure on a graded vector space V consists of degree 1 linear map $\{\theta_k\}_{k=1}^{\infty}$ from the graded vector space $\text{Sym}(V) \otimes V$ to V such that $\sum_{k=1}^{+\infty} \theta_k$ is a Maurer-Cartan element of the graded Lie algebra $(C^*(V, V), [\cdot, \cdot]_{MN})$.

From pre-Lie $_{\infty}$ -algebras to homotopy RB operators

Let $(\mathfrak{g}, \{\theta_k\}_{k=1}^{+\infty})$ be a pre-Lie $_{\infty}$ -algebra. Define l_k by

$$l_k(x_1, \dots, x_k) = \sum_{i=1}^k (-1)^{x_i(x_{i+1} + \dots + x_k)} \theta_k(x_1, \dots, \hat{x}_i, \dots, x_k, x_i).$$

Then $(\mathfrak{g}, \{l_k\}_{k=1}^{+\infty})$ is an L_{∞} -algebra, denoted by \mathfrak{g}^C .

For all $k \geq 1$, we define $L_k : \text{Sym}^{k-1}(\mathfrak{g}) \rightarrow \mathfrak{gl}(\mathfrak{g})$ by

$$L_k(x_1, \dots, x_{k-1})(x_k) = \theta_k(x_1, \dots, x_{k-1}, x_k).$$

Proposition

With the above notation, $(\mathfrak{g}, \{L_k\}_{k=1}^{+\infty})$ is a representation of the sub-adjacent L_{∞} -algebra \mathfrak{g}^C . Moreover, *the identity map* $\text{Id} : \mathfrak{g} \rightarrow \mathfrak{g}$ *is a strict* **homotopy relative Rota-Baxter operator** *on the* L_{∞} -algebra \mathfrak{g}^C *with respect to the representation* $(\mathfrak{g}, \{L_k\}_{k=1}^{+\infty})$.

Theorem (Lazarev-S.-Tang)

Let $T \in \text{Hom}(V, \mathfrak{g})$ be a strict *homotopy relative Rota-Baxter operator* on an L_{∞} -algebra $(\mathfrak{g}, \{l_k\}_{k=1}^{+\infty})$ with respect to the representation $(V, \{\rho_k\}_{k=1}^{+\infty})$. Then $(V, \{\theta_k\}_{k=1}^{+\infty})$ is a *pre-Lie $_{\infty}$ -algebra*, where $\theta_k : \otimes^k V \rightarrow V$ ($k \geq 1$) are linear maps of degree 1 defined by

$$\theta_k(v_1, \dots, v_k) := \rho_k(Tv_1, \dots, Tv_{k-1}, v_k), \quad \forall v_1, \dots, v_k \in V.$$

The notion of an r_∞ -matrix was introduced by A. Voronov and his collaborators in



D. Bashkirov and **A. Voronov**, r_∞ -Matrices, triangular L_∞ -bialgebras, and quantum $_\infty$ groups, 2015.

As expected, an r_∞ -matrix gives rise to a homotopy relative Rota-Baxter operator with respect to the coadjoint representation.

Definition

A **V-structure** consists of a quadruple $(L, \mathfrak{h}, P, \Delta)$ where

- $(L, [\cdot, \cdot])$ is a graded Lie algebra,
- \mathfrak{h} is an abelian graded Lie subalgebra of $(L, [\cdot, \cdot])$,
- $P : L \longrightarrow L$ is a projection, that is $P \circ P = P$, whose image is \mathfrak{h} and kernel is a graded Lie subalgebra of $(L, [\cdot, \cdot])$,
- Δ is an element in $\ker(P)^1$ such that $[\Delta, \Delta] = 0$.

Theorem (T. Voronov)

Let $(L, \mathfrak{h}, P, \Delta)$ be a V -structure. Then the graded vector space $L[1] \oplus \mathfrak{h}$ is an L_∞ -algebra where

$$l_1(x, a) = (-[\Delta, x], P(x + [\Delta, a])),$$

$$l_2(x, y) = (-1)^x [x, y],$$

$$l_k(x, a_1, \dots, a_{k-1}) = P[\dots [[x, a_1], a_2] \dots, a_{k-1}], \quad k \geq 2,$$

$$l_k(a_1, \dots, a_{k-1}, a_k) = P[\dots [[\Delta, a_1], a_2] \dots, a_k], \quad k \geq 2.$$

Here $a, a_1, \dots, a_k \in \mathfrak{h}$ and $x, y \in L$.

Remark

Let L' be a graded Lie subalgebra of L that satisfies $[\Delta, L'] \subset L'$. Then $L'[1] \oplus \mathfrak{h}$ is an L_∞ -subalgebra of the above L_∞ -algebra $(L[1] \oplus \mathfrak{h}, \{l_k\}_{k=1}^{+\infty})$.

A V -structure

Let \mathfrak{g} and V be two vector spaces.

Proposition (Lazarev-S.-Tang)

We have a V -structure $(L, \mathfrak{h}, P, \Delta)$ as follows:

- the graded Lie algebra $(L, [\cdot, \cdot])$ is given by

$$\left(\bigoplus_{n=0}^{+\infty} C^{n+1}(\mathfrak{g} \oplus V, \mathfrak{g} \oplus V), [\cdot, \cdot]_{\text{NR}} \right);$$

- the abelian graded Lie subalgebra \mathfrak{h} is given by

$$\mathfrak{h} := \bigoplus_{n=0}^{+\infty} \text{Hom}(\wedge^{n+1} V, \mathfrak{g});$$

- $P : L \rightarrow L$ is the projection onto the subspace \mathfrak{h} , and $\Delta = 0$.

Consequently, we obtain an L_∞ -algebra $(L[1] \oplus \mathfrak{h}, \{l_k\}_{k=1}^{+\infty})$,

$$l_1(Q, \theta) = P(Q),$$

$$l_2(Q, Q') = (-1)^Q [Q, Q']_{\text{NR}},$$

$$l_k(Q, \theta_1, \dots, \theta_{k-1}) = P[\dots [Q, \theta_1]_{\text{NR}}, \dots, \theta_{k-1}]_{\text{NR}},$$

for $\theta, \theta_1, \dots, \theta_{k-1} \in \mathfrak{h}$, $Q, Q' \in L$.

Main Theorem

Note that $L' = \bigoplus_{k=0}^{+\infty} (\text{Hom}(\wedge^{n+1} \mathfrak{g}, \mathfrak{g}) \oplus \text{Hom}(\wedge^n \mathfrak{g} \otimes V, V))$ is a subalgebra of L .

Theorem (Lazarev-S.-Tang)

With above notation, $(L'[1] \oplus \mathfrak{h}, \{l_k\}_{k=1}^{+\infty})$ is an L_∞ -algebra, where l_k are given by

$$\begin{aligned}l_2(Q, Q') &= (-1)^Q [Q, Q']_{\text{NR}}, \\l_k(Q, \theta_1, \dots, \theta_{k-1}) &= P[\dots [Q, \theta_1]_{\text{NR}}, \dots, \theta_{k-1}]_{\text{NR}},\end{aligned}$$




for $\theta_1, \dots, \theta_{k-1} \in \mathfrak{h}$, $Q, Q' \in L'$.

Let $\mu \in \text{Hom}(\wedge^2 \mathfrak{g}, \mathfrak{g})$, $\rho \in \text{Hom}(\mathfrak{g} \otimes V, V)$, $T \in \text{Hom}(V, \mathfrak{g})$. Then $((\mathfrak{g}, \mu), \rho, T)$ is a **relative Rota-Baxter Lie algebra** if and only if $\mu + \rho + T$ is a **Maurer-Cartan element of the L_∞ -algebra** $(L'[1] \oplus \mathfrak{h}, \{l_i\}_{i=1}^{+\infty})$.

Let $\mu + \rho + T$ be a Maurer-Cartan element. Then we have

$$\begin{aligned}
 & \sum_{k=1}^{+\infty} \frac{1}{k!} l_k(\mu + \rho + T, \dots, \mu + \rho + T) \\
 &= \frac{1}{2!} l_2(\mu + \rho + T, \mu + \rho + T) \\
 & \quad + \frac{1}{3!} l_3(\mu + \rho + T, \mu + \rho + T, \mu + \rho + T) \\
 &= \left(-\frac{1}{2} [\mu + \rho, \mu + \rho]_{\text{NR}}, \frac{1}{2} [[\mu + \rho, T]_{\text{NR}}, T]_{\text{NR}} \right) \\
 &= (0, 0).
 \end{aligned}$$

Thus, we obtain $[\mu + \rho, \mu + \rho]_{\text{NR}} = 0$ and $[[\mu + \rho, T]_{\text{NR}}, T]_{\text{NR}} = 0$, which implies that (\mathfrak{g}, μ) is a Lie algebra, $(V; \rho)$ is its representation and T is a relative Rota-Baxter operator on the Lie algebra (\mathfrak{g}, μ) with respect to the representation $(V; \rho)$.

-  R. Tang, C. Bai, L. Guo and Y. Sheng, Deformations and their controlling cohomologies of \mathcal{O} -operators, *Comm. Math. Phys.* 368 (2019), 665 – 700.
-  A. Lazarev, Y. Sheng and R. Tang, Deformations and homotopy theory of relative Rota-Baxter Lie algebras. arXiv:2008.06714.
-  A. Lazarev, Y. Sheng and R. Tang, Homotopy relative Rota-Baxter Lie algebras, triangular L_∞ -bialgebras and higher derived brackets. arXiv:2008.00059.

Thanks for your attention!