

Frédéric Legoll<sup>1</sup>, Tony Lelièvre<sup>1</sup>, Keith Myerscough<sup>2</sup> and Giovanni Samaey<sup>2</sup>  
<sup>1</sup>Ecole des Ponts ParisTech, <sup>2</sup>KU Leuven

## In a nutshell

- Goal** Simulate slow-fast SDEs over long time, quickly
- Model** Slow-fast system of SDEs, and a macroscopic model taken from the "fast" limit
- Method** Parallel-in-time algorithm that iteratively improves the macroscopic result
- Result** Reduction in wall clock time
- Bonus** Lower variance than full microscopic model

## Microscopic model

- Slow-fast system of coupled SDEs
 
$$dX = (-X_t^3 + X_t + Y_t^2) dt + \sqrt{\frac{2}{\beta}} dB_t^{(x)}$$

$$dY = \frac{1}{\epsilon}(X_t - Y_t) dt + \sqrt{\frac{2}{\beta\epsilon}} dB_t^{(y)}$$
- Modeled as an ensemble  $\mathcal{X}_t$  of particles with positions  $(X_t^p, Y_t^p)$  and weight  $W^p$
- Time integrator: a Lie-Trotter splitting, updating  $X_t$  first, then  $Y_t$
- Validation: *deterministic* solution given by the Fokker-Planck equation, akin to the macroscopic model

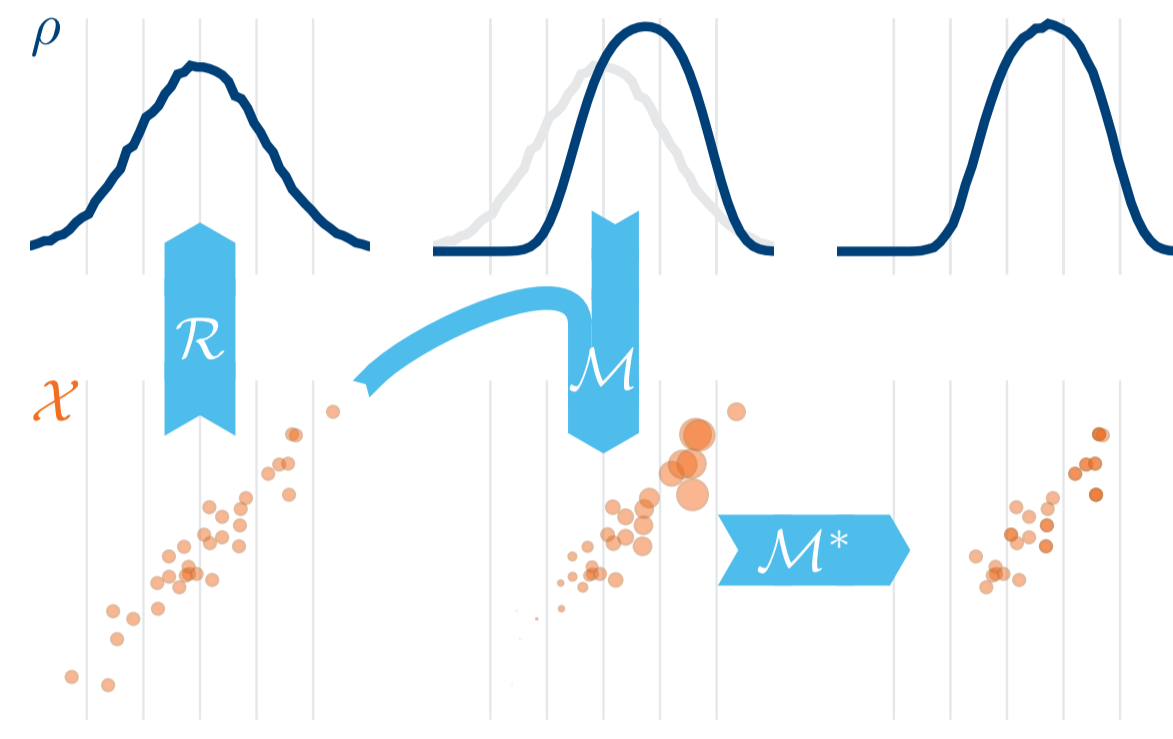
## Macroscopic model

- Only slow variable, *assume* the fast  $Y_t$  is equilibrated and use only the expected value of the term  $Y_t^2$ 

$$dZ = (-Z_t^3 + Z_t + Z_t^2 + \frac{1}{\beta}) dt + \sqrt{\frac{2}{\beta}} dB_t^{(z)},$$
 or in potential form
 
$$dZ = -\partial_z V_{\text{eff}}(Z_t) dt + \sqrt{\frac{2}{\beta}} dB_t^{(z)}.$$
- The associated Fokker-Planck equation reads
 
$$\partial_t \rho(z) = \partial_z (\rho(z) \partial_z V_{\text{eff}}) + \frac{1}{\beta} \partial_{zz} \rho(z).$$
- The macroscopic state is represented by integral quantities over a regular grid

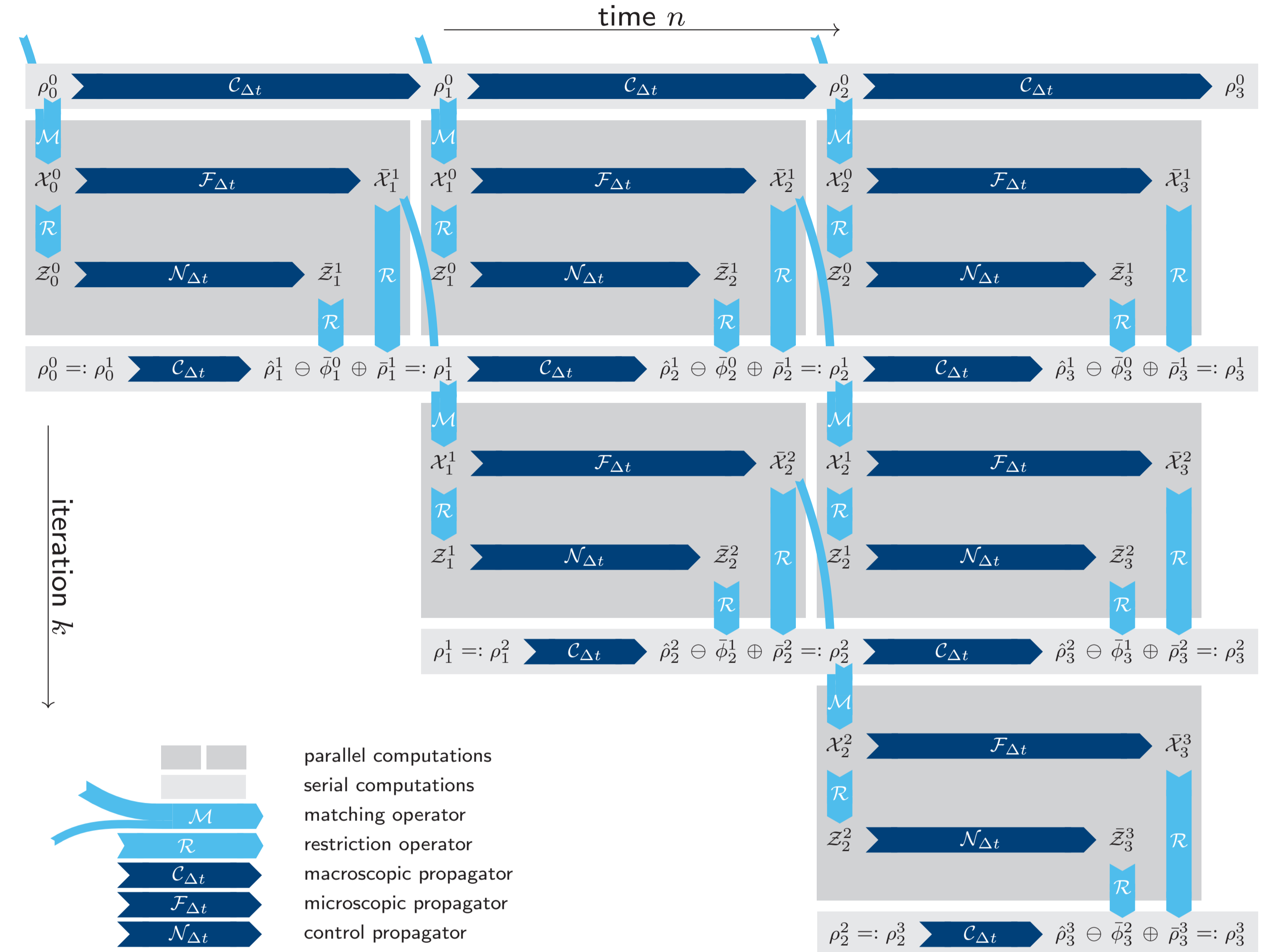
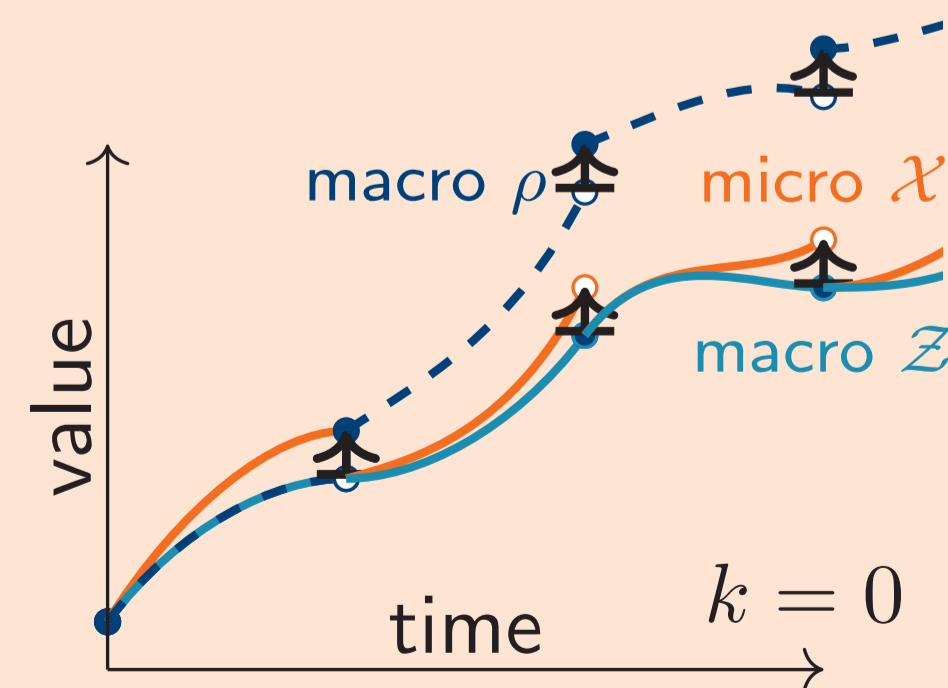
## Coupling

- Restriction** ( $\mathcal{R}$ , from micro to macro) sum the weights of all particles in each bin
- Matching** ( $\mathcal{M}$ , from macro to micro) reweight particles from a known microstate  $(\bar{X}^p, \bar{Y}^p, \bar{W}^p)$
- Resampling** ( $\mathcal{M}^*$ , optional) retrieve an ensemble with all particles equal in weight



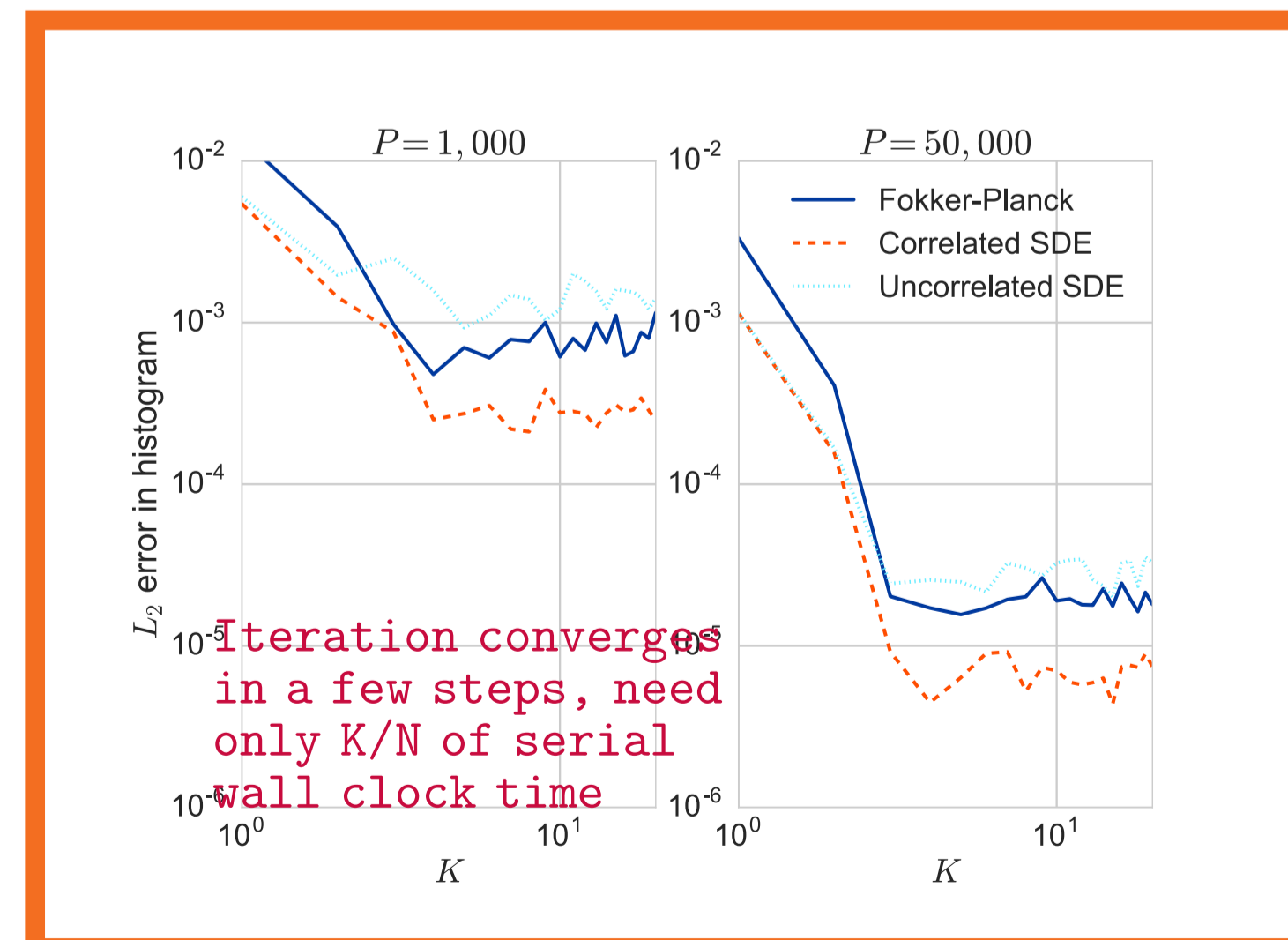
## The parareal algorithm

- Iteratively improves** the macroscopic propagator by computing the discrepancies between the macroscopic and the *microscopic* models *in parallel*
- Parallel** use of the microscopic propagator gives a reduction in *wall clock time* if there are fewer iterations needed than time steps
- Variance** of the stochastic microscopic propagator dominates the error (see figures →)
- Reduction in variance** by using a particle propagator with *correlated noise* for the macroscopic model in computing the discrepancies between the models

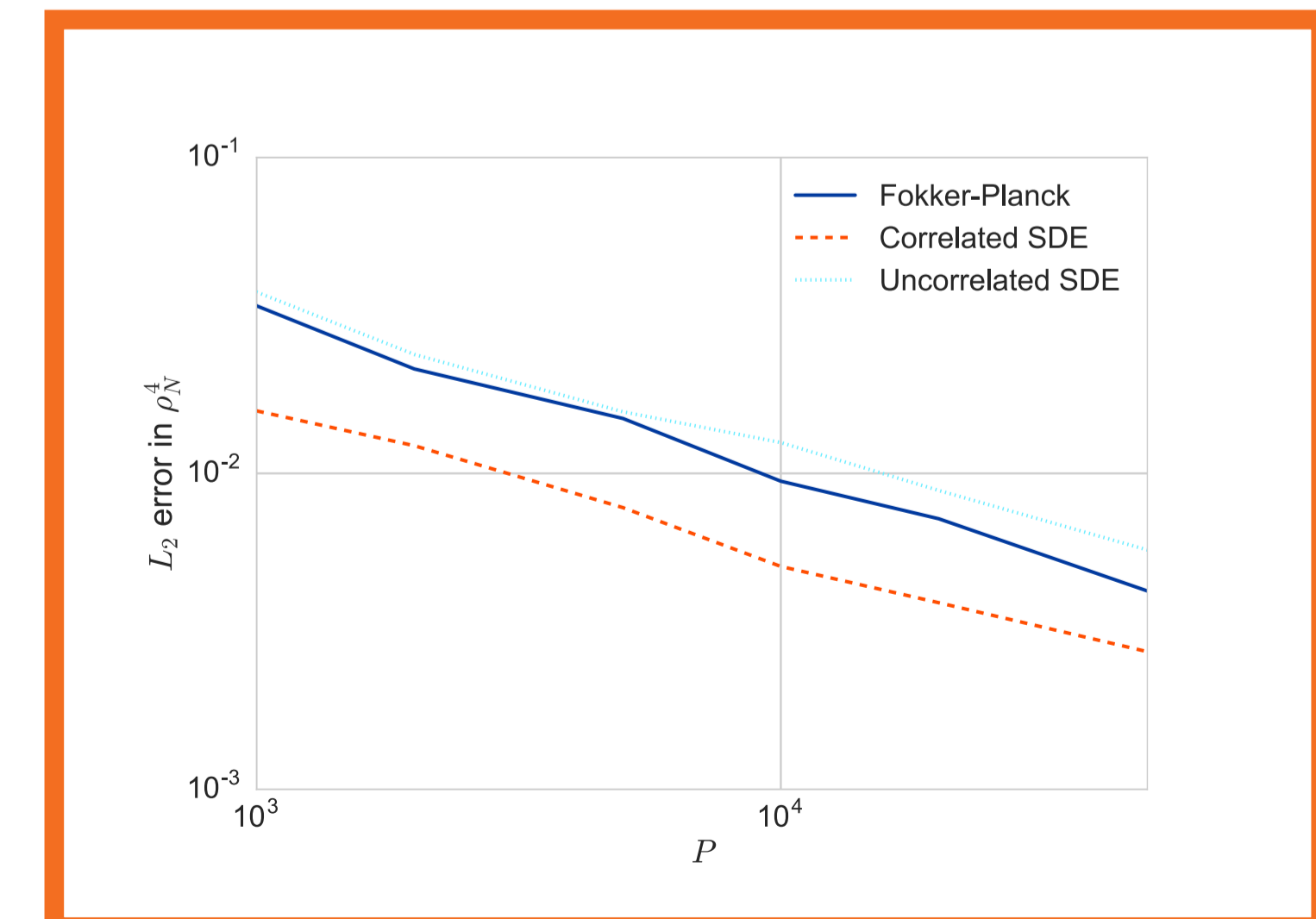


Parameters used below:  $\beta = 5, \epsilon = 0.1, K = N = 20, \Delta t = 0.025, \delta t = 1.0 \times 10^{-4}$

## Convergence in iterations



## Convergence in number of particles



Keith Myerscough  
 keith.myerscough@kuleuven.be  
 people.cs.kuleuven.be/~keith.myerscough/

In association with:



Department of Computer Science

